

PAT 464/564 (Winter 2026)

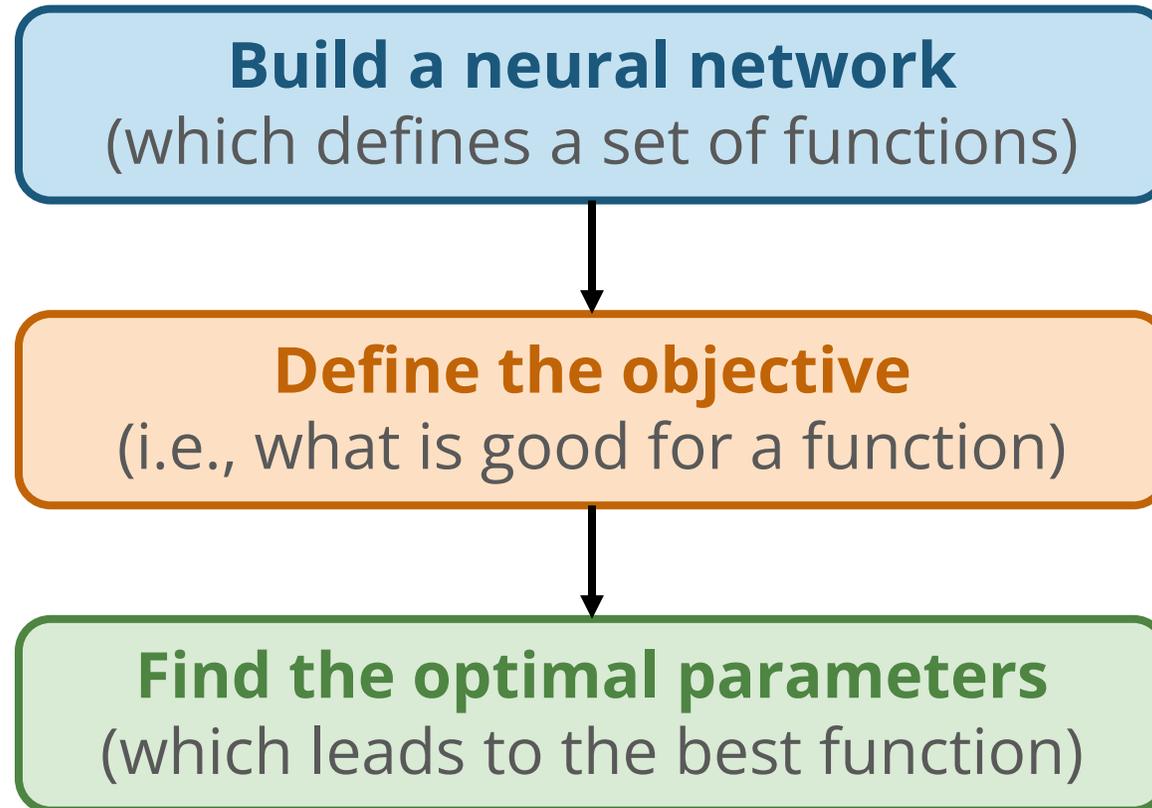
Generative AI for Music & Audio Creation

Lecture 7: Deep Learning Fundamentals II

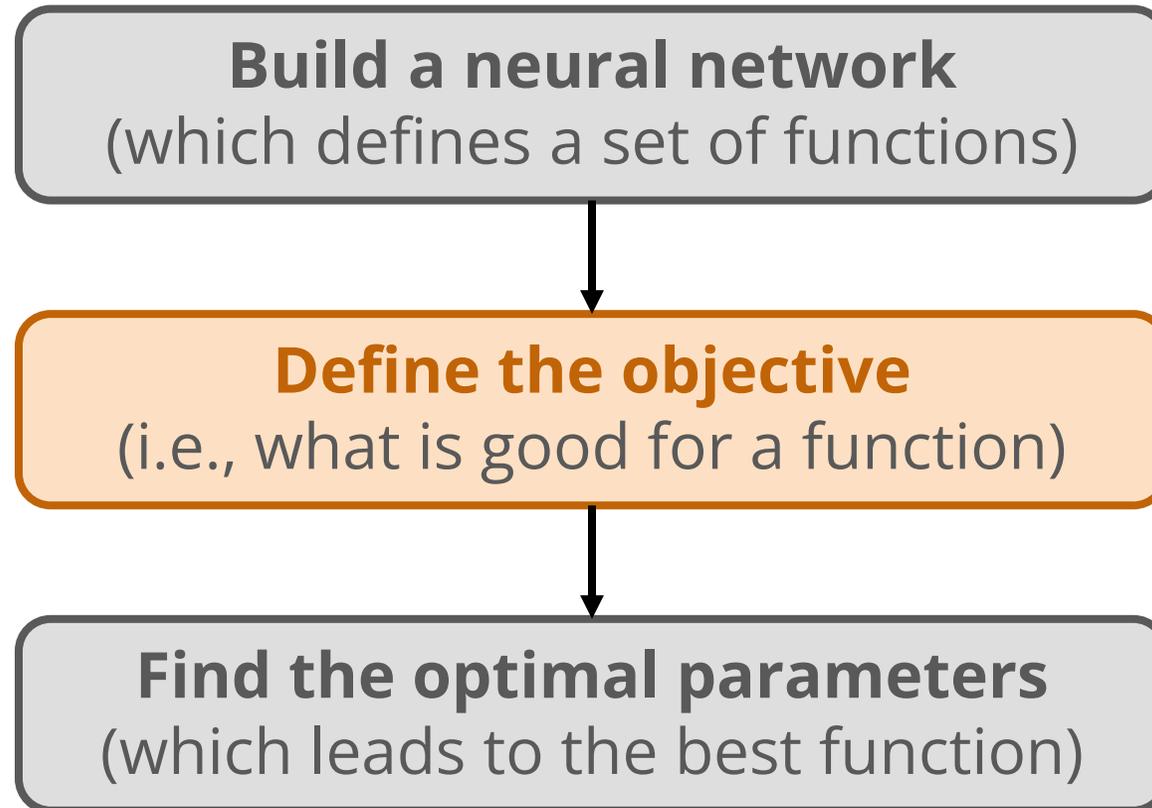
Instructor: Hao-Wen Dong

Training a Neural Network

| Training a Neural Network

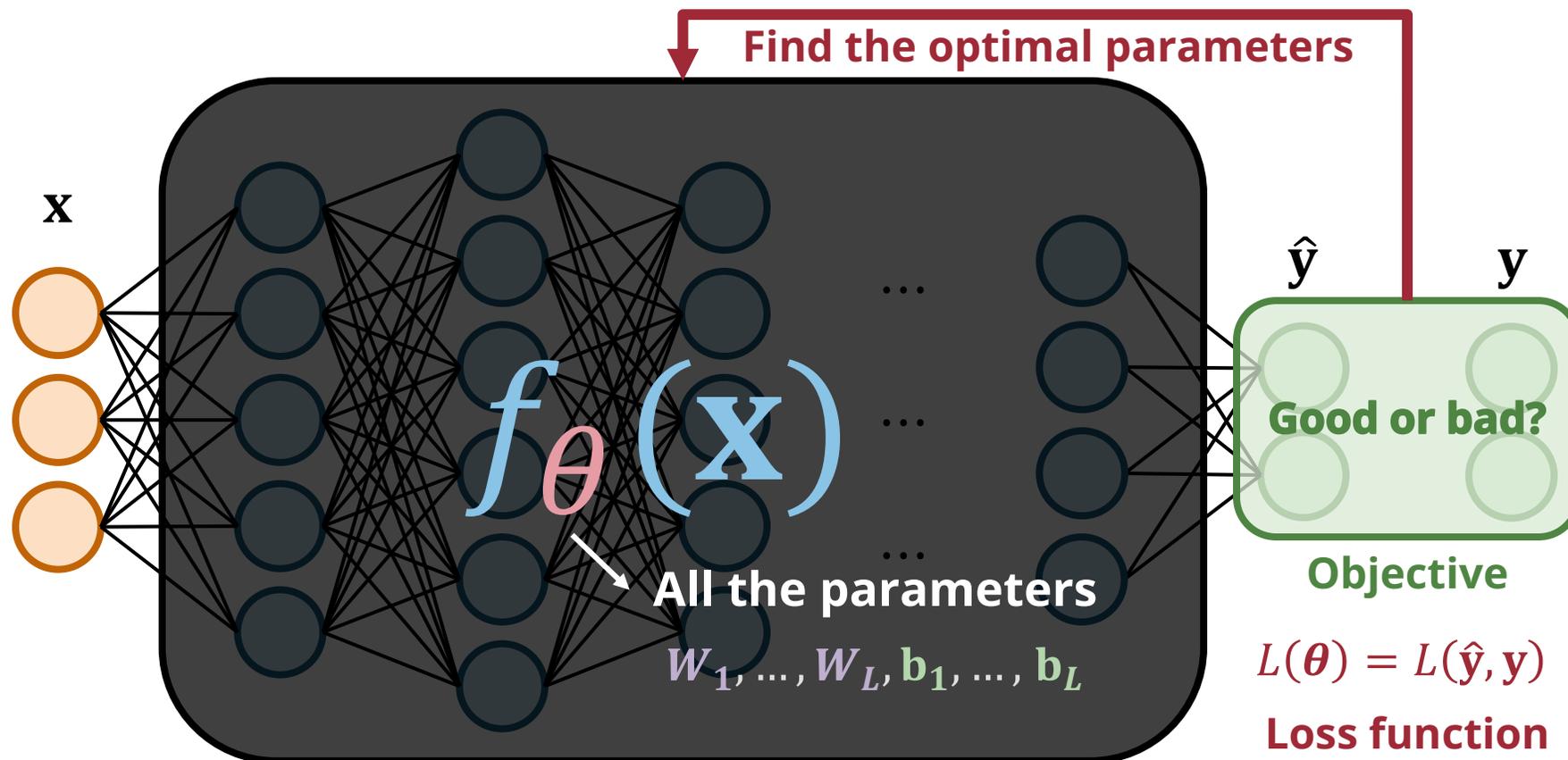


| Training a Neural Network



Neural Networks are Parameterized Functions

- A neural network represents **a set of functions**



Loss Function

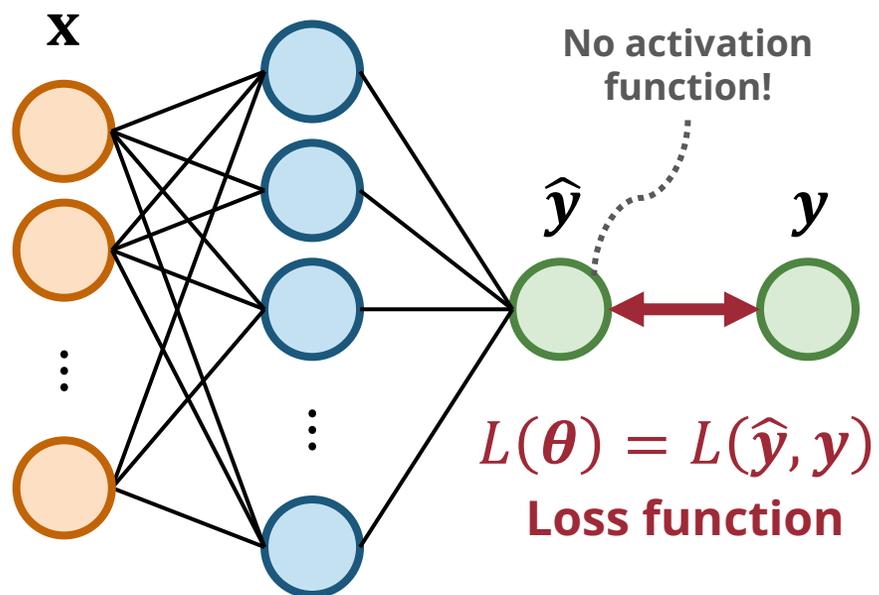
- Measure **how well the model perform** (in the opposite way)
- The choice of loss function depends on the task and the goals

$$L(\boldsymbol{\theta}) = L(\hat{\mathbf{y}}, \mathbf{y})$$

Loss Function: The Many Names

- Sometimes called
 - **Cost** function
 - **Error** function
- The opposite is known as
 - **Objective** function
 - **Reward** function (reinforcement learning)
 - **Fitness** function (evolutionary algorithms & genetic algorithms)
 - **Utility** function (economics)
 - **Profit** function (economics)

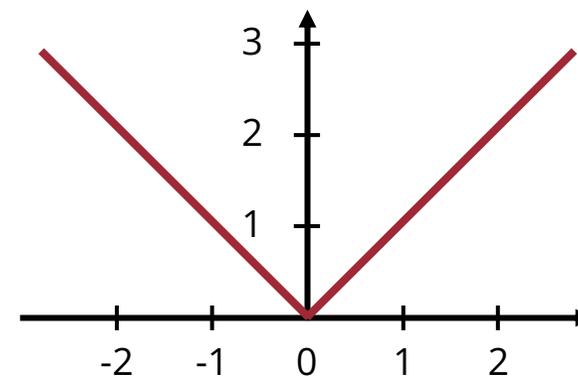
Common Loss Functions for Regression



Why not $L(\hat{y}, y) = \hat{y} - y$?

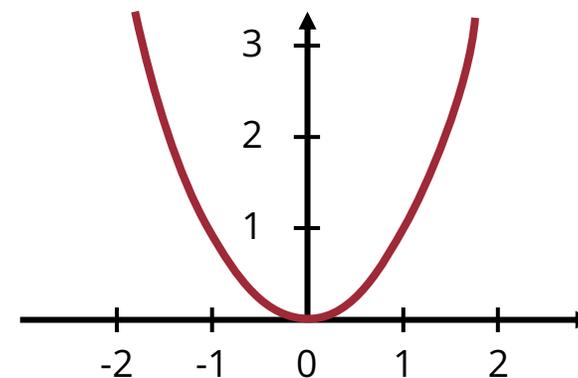
L1 loss

$$L(\hat{y}, y) = |\hat{y} - y|$$



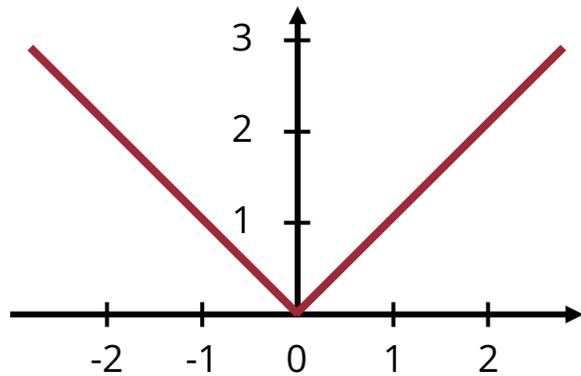
L2 loss

$$L(\hat{y}, y) = (\hat{y} - y)^2$$



L1 vs L2 Losses

L1 loss

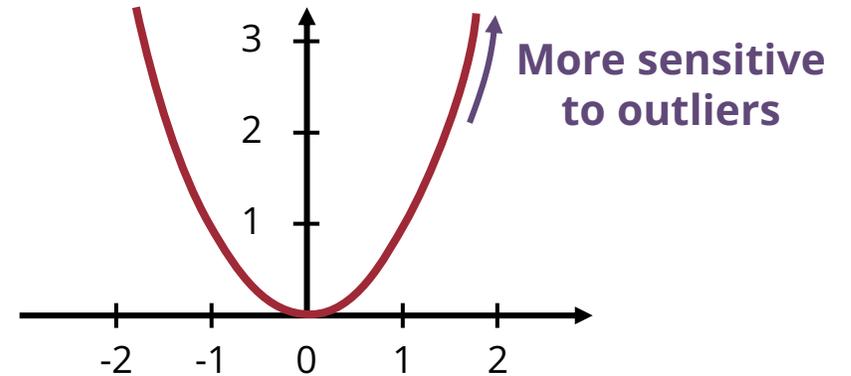


$$L(\hat{y}, y) = |\hat{y} - y|$$

$$L(\hat{\mathbf{y}}, \mathbf{y}) = \mathbf{MAE}(\hat{\mathbf{y}}, \mathbf{y}) = \frac{1}{n} \sum_{i=1}^n |\hat{y}_i - y_i|$$

Mean Absolute Error (MAE)

L2 loss



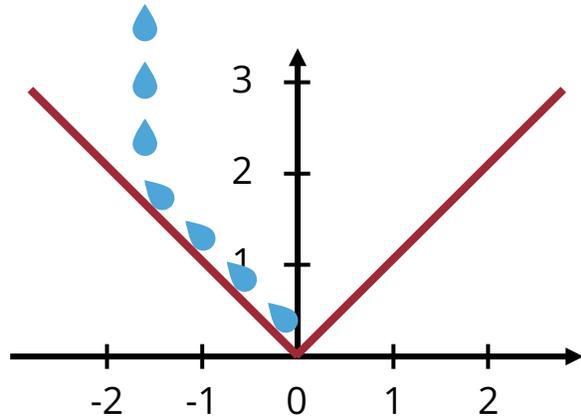
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Mean Squared Error (MSE)

L1 vs L2 Losses

L1 loss

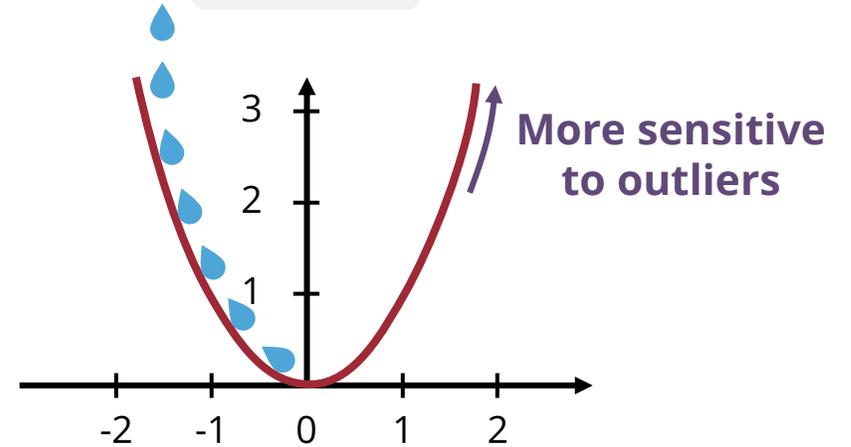


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Mean Absolute Error (MAE)

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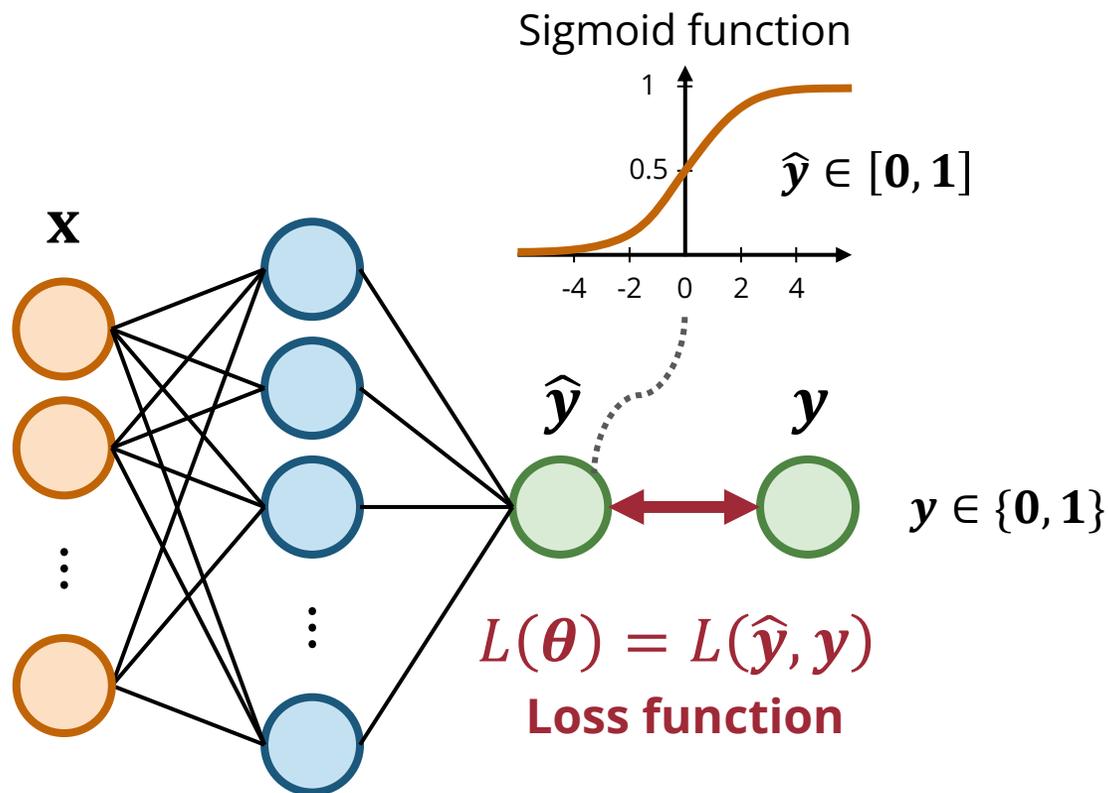
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Mean Squared Error (MSE)

Binary Cross Entropy for Binary Classification

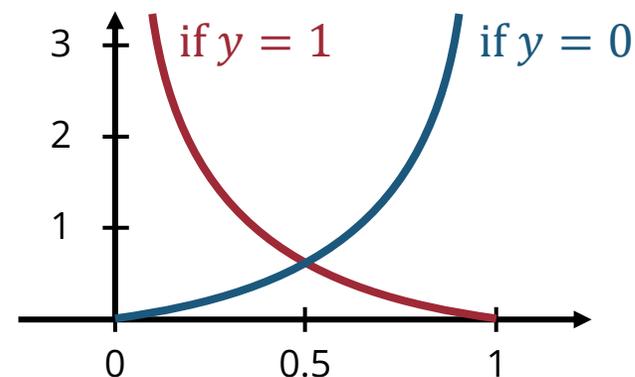
- **Logistic regression** approaches classification like regression



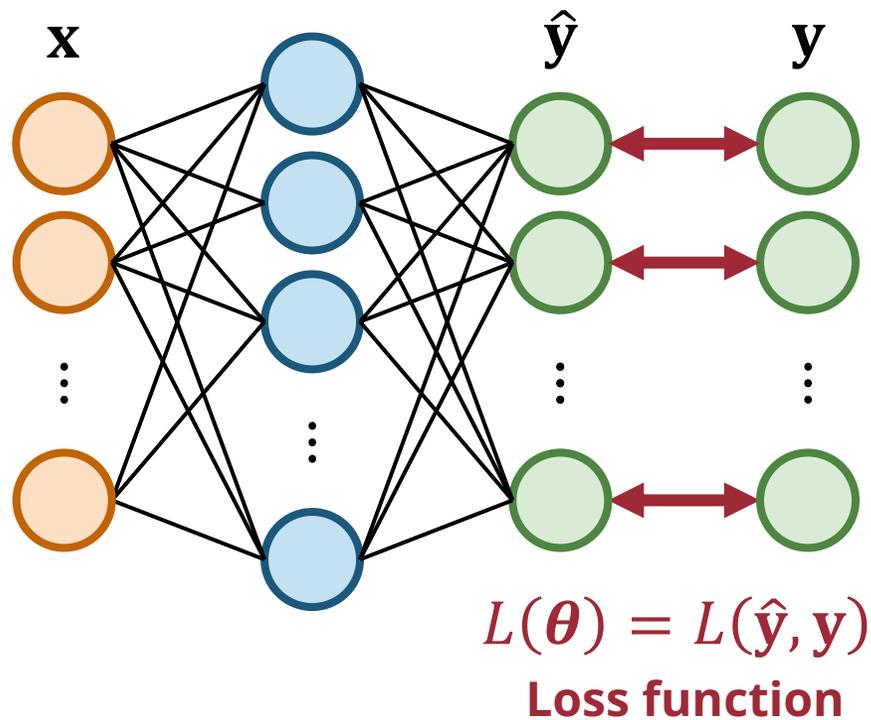
Binary cross entropy

(Also called log loss)

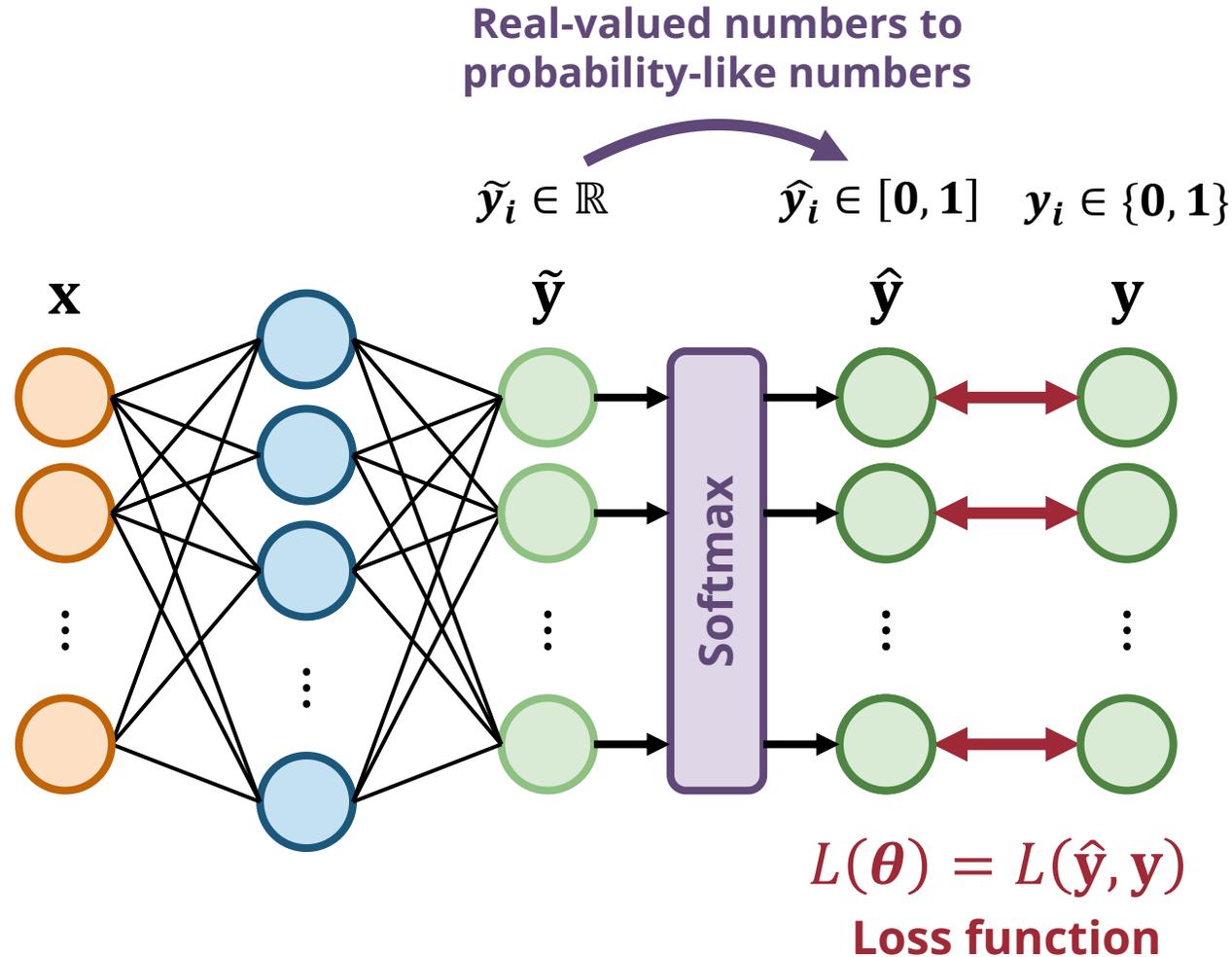
$$L(\hat{y}, y) = \begin{cases} -\log \hat{y}, & \text{if } y = 1 \\ -\log(1 - \hat{y}), & \text{if } y = 0 \end{cases}$$
$$= -y \log \hat{y} - (1 - y) \log(1 - \hat{y})$$



Cross Entropy for Multiclass Classification



Cross Entropy for Multiclass Classification



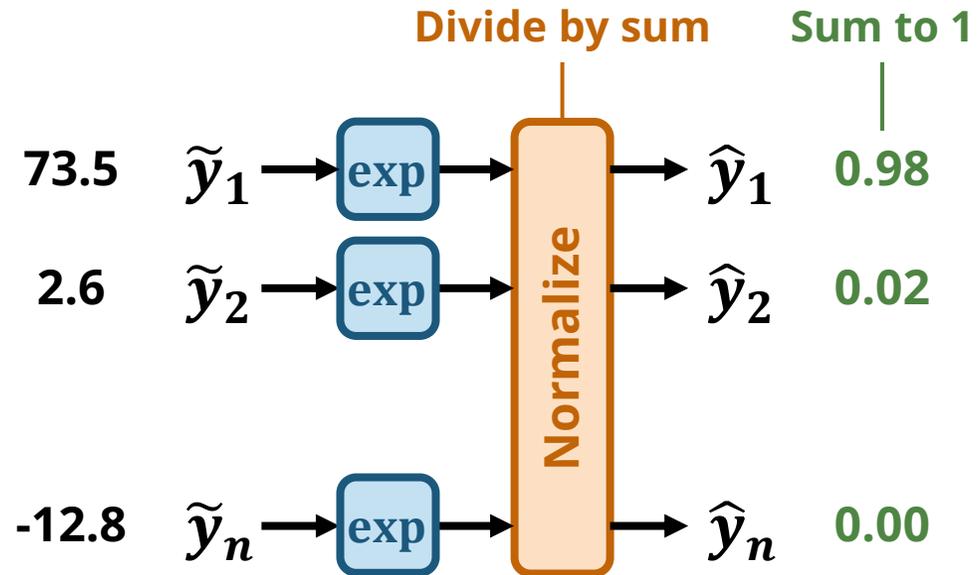
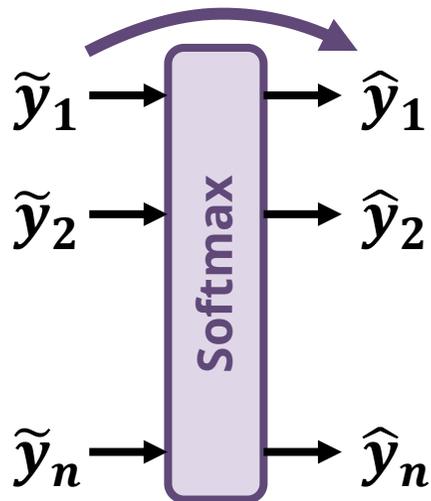
Softmax

$$\hat{y}_i = \frac{e^{\tilde{y}_i}}{\sum_{j=1}^n e^{\tilde{y}_j}}$$

Softmax

- **Intuition:** Map several numbers to $[0, 1]$ while **keeping their relative magnitude**
 - Softmax is like the **multivariate version of sigmoid**

Real-valued numbers to probability-like numbers



Cross Entropy for Multiclass Classification

Binary Cross Entropy

Only one of them will be one!

$$L(\hat{y}, y) = -y \log \hat{y} - (1 - y) \log(1 - \hat{y})$$

Cross Entropy

Only one of them will be one!

$$L(\hat{\mathbf{y}}, \mathbf{y}) = -y_1 \log \hat{y}_1 - y_2 \log \hat{y}_2 - \dots - y_i \log \hat{y}_i$$

$$= -\sum_i^n y_i \log \hat{y}_i$$

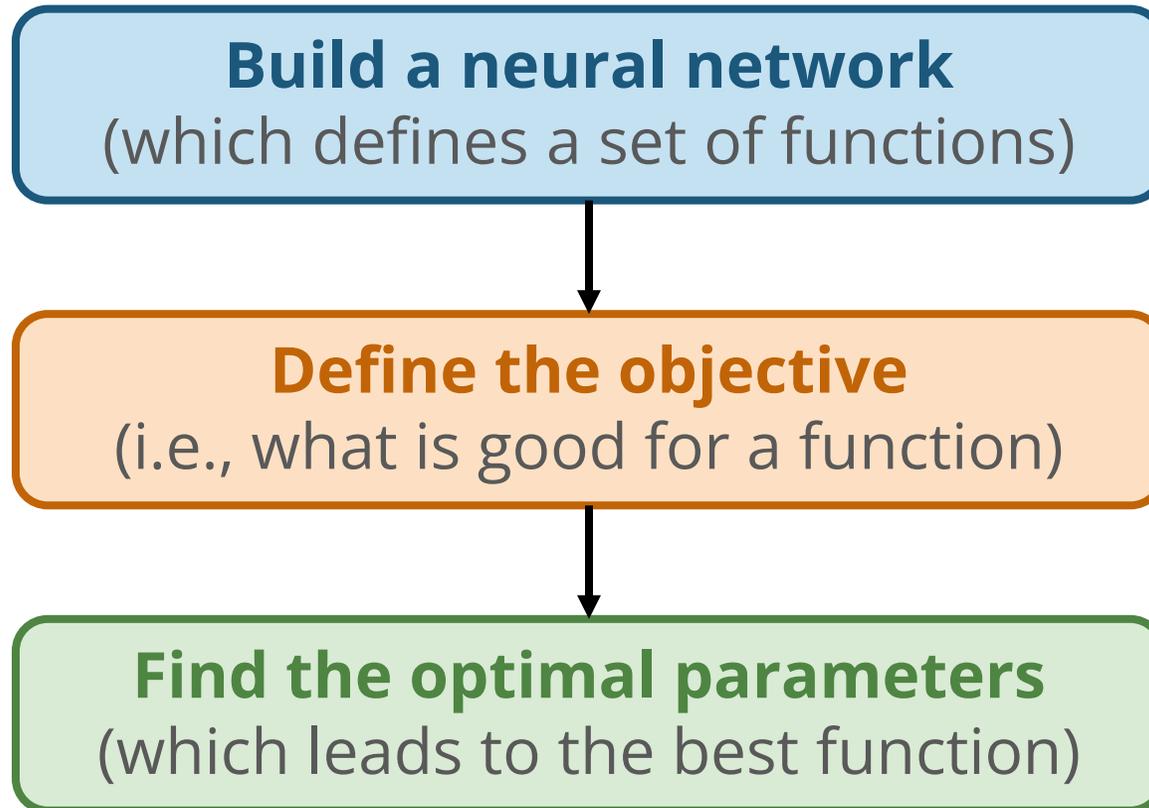
Log likelihood

In Practice: Audio Codec

- What would be **a good objective to train a neural audio codec?**
- What do we **care about** for a codec?
 - Reconstruction quality **Trainable**
 - Bit rate (compression rate) **Likely not trainable but searchable**
 - Encoding/decoding speed **Likely not trainable but searchable**
- How do we measure **reconstruction quality?**
 - Difference in raw waveforms?
 - Difference in spectrograms?
 - Perceptual quality (psychoacoustics)?

Optimization

Training a Neural Network

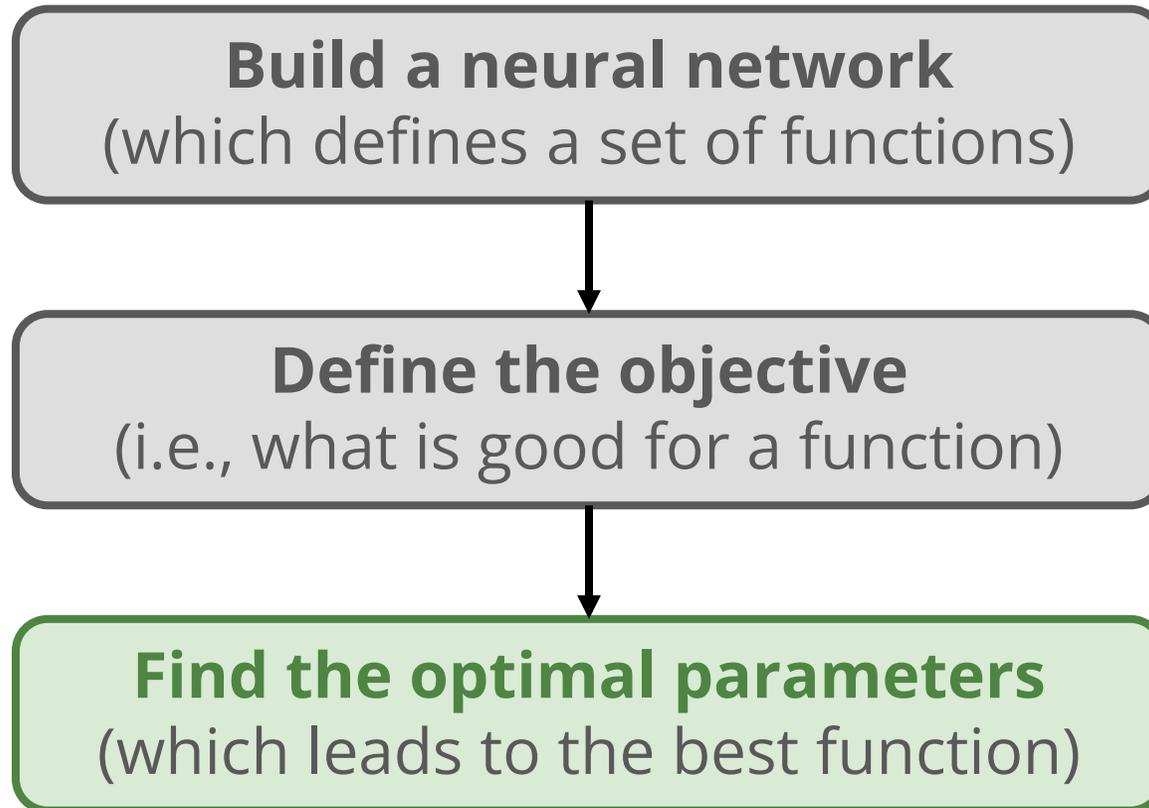


$$\hat{y} = f_{\theta}(\mathbf{x})$$

$$L(\theta)$$

$$\theta^* = \arg \min_{\theta} L(\theta)$$

Training a Neural Network



$$\hat{y} = f_{\theta}(\mathbf{x})$$

$$L(\theta)$$

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Optimizing the Parameters of a Neural Network

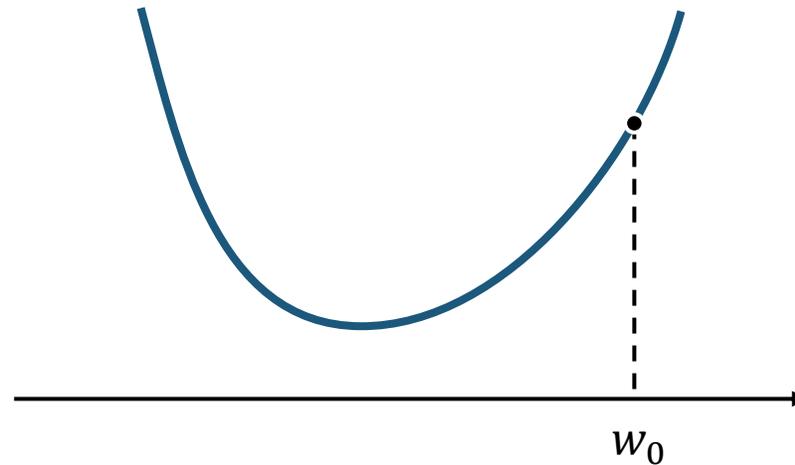
- Many, many ways...
- Most commonly through **gradient descent** in deep learning
- Alternatively, we can use search or genetic algorithm

$$\theta^* = \arg \min_{\theta} L(\theta)$$

Gradient Descent

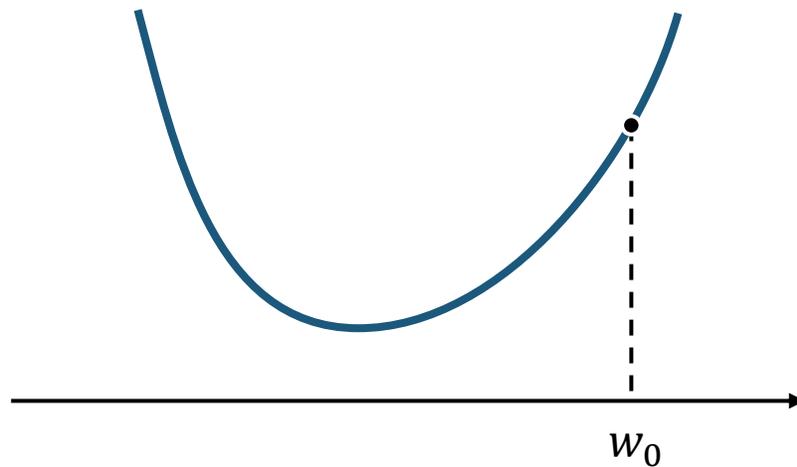
- **Intuition:** Gradient can suggest a good direction to tune the parameters

Derivative for a vector,
matrix or tensor



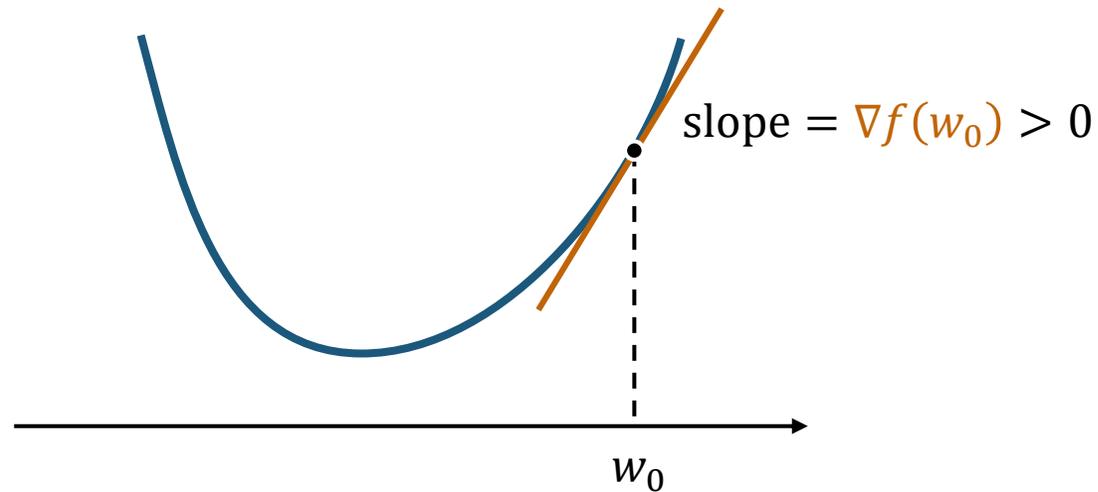
Gradient Descent: Pseudocode

- Pick an **initial weight vector** w_0 and **learning rate** η
- Repeat until convergence: $w_{t+1} = w_t - \eta \nabla f(w_t)$ → **Gradient of function f with respect to weight w**



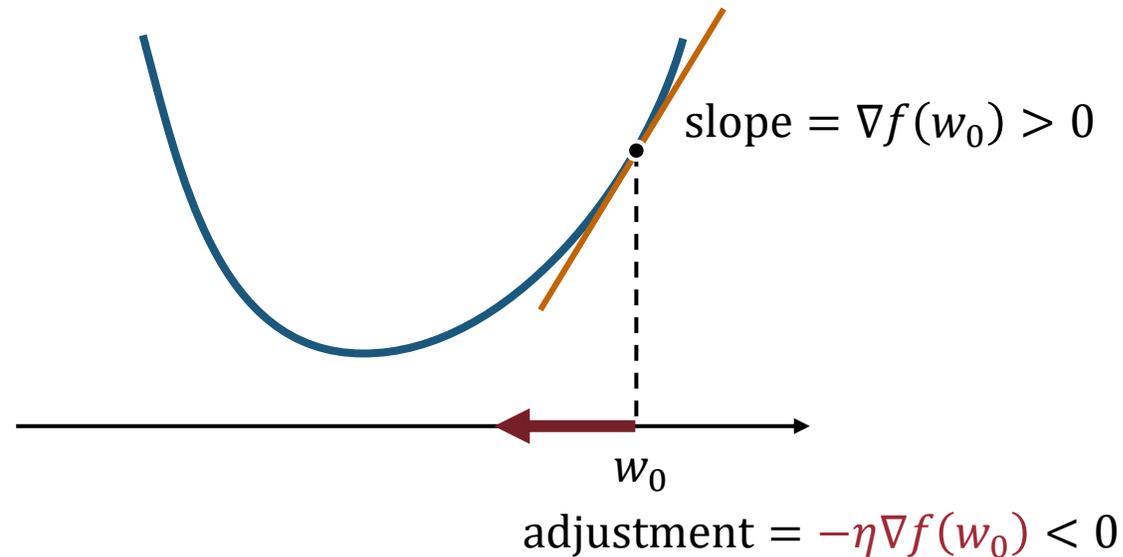
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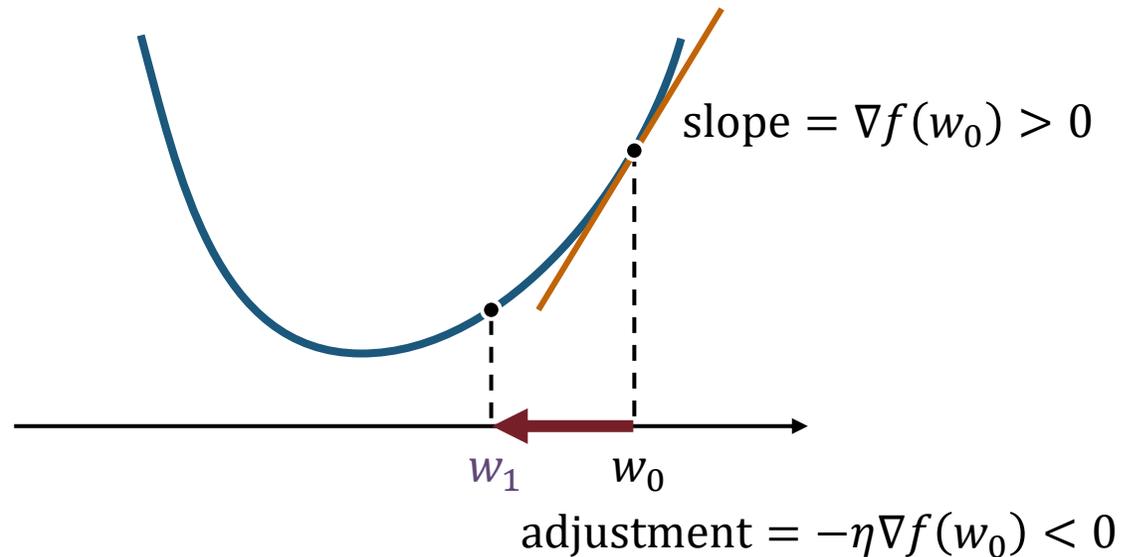
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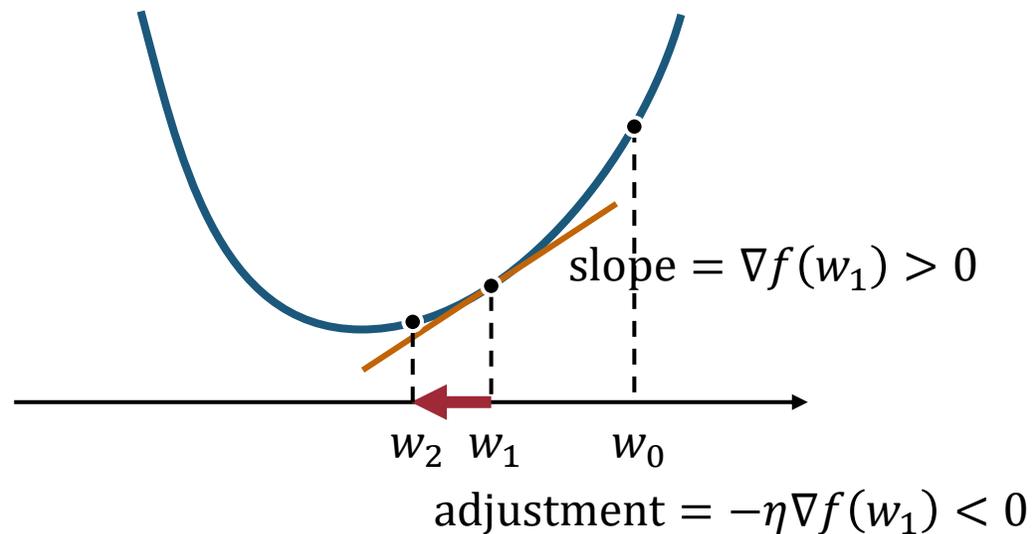
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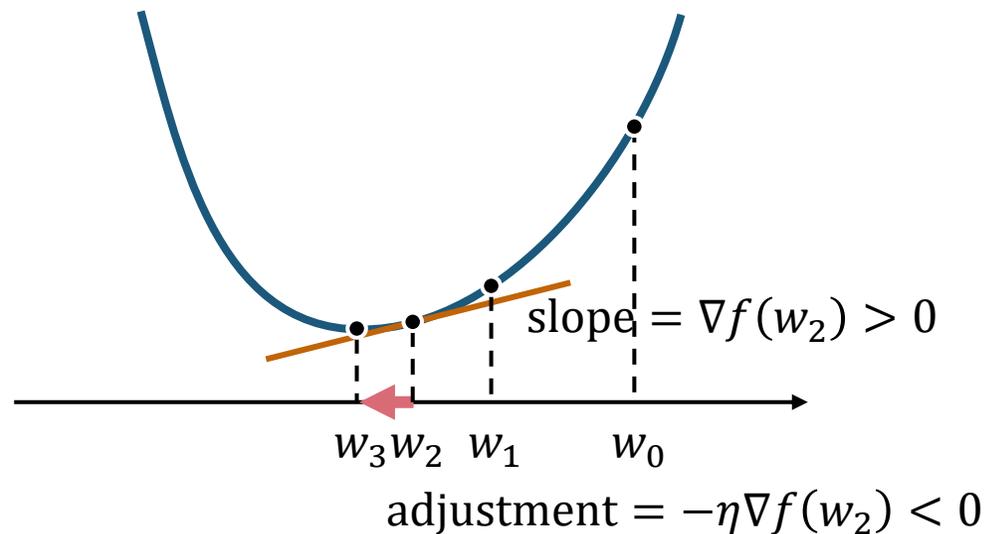
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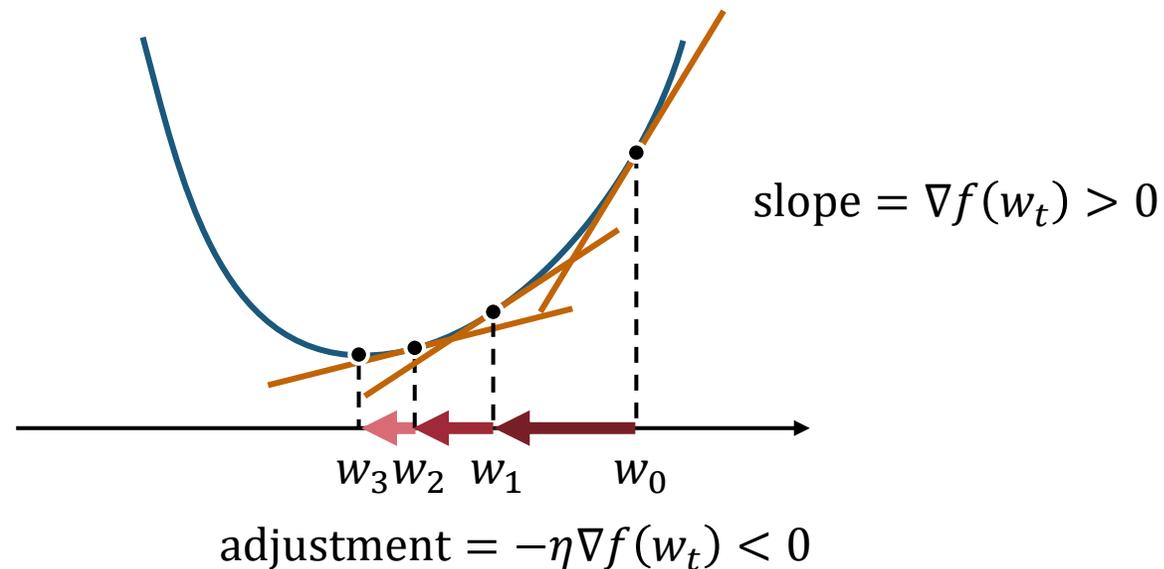
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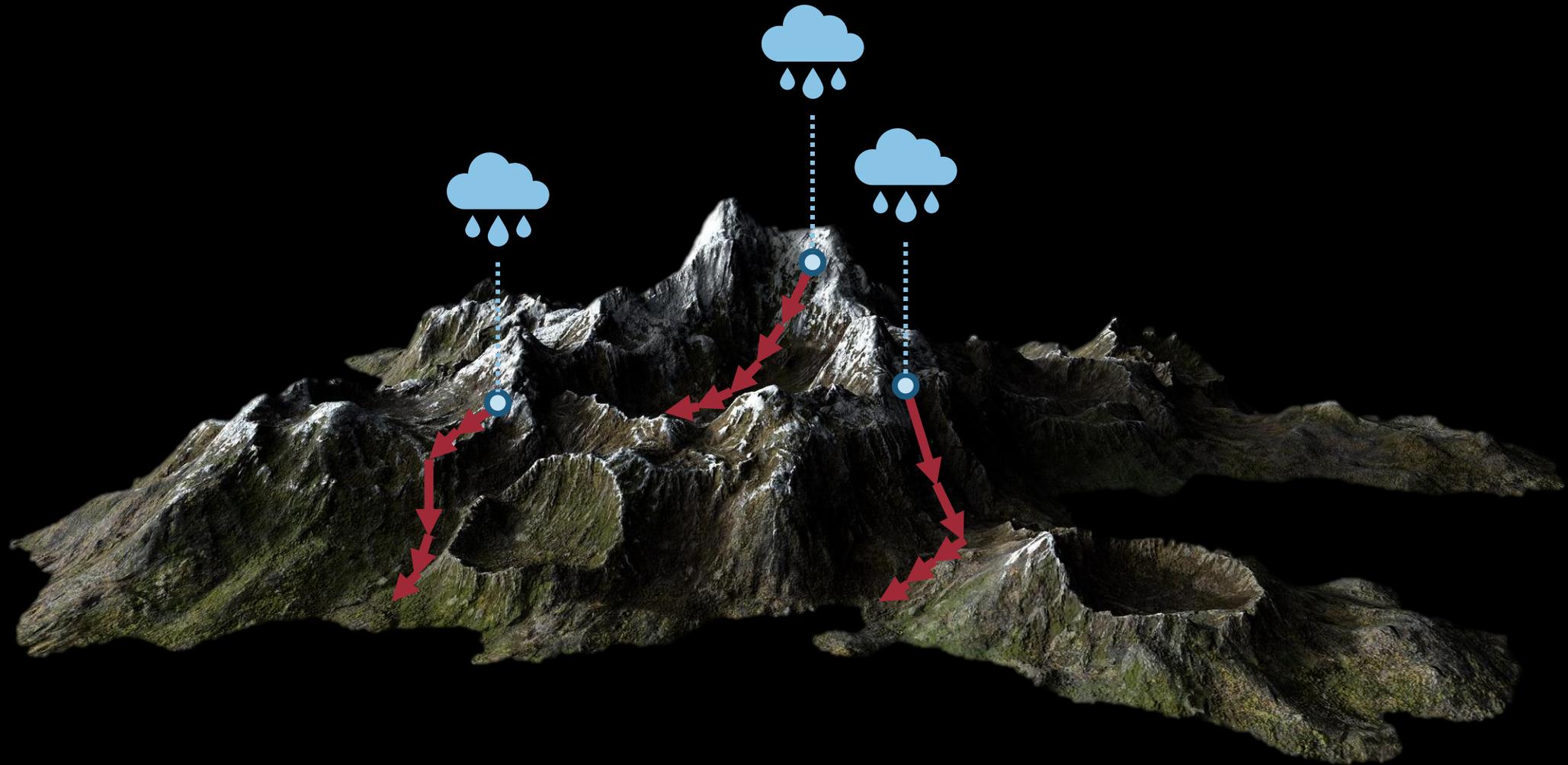


Gradient Descent: Pseudocode

- Pick an initial weight vector w_0 and learning rate η
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Gradient Descent: 3D Case

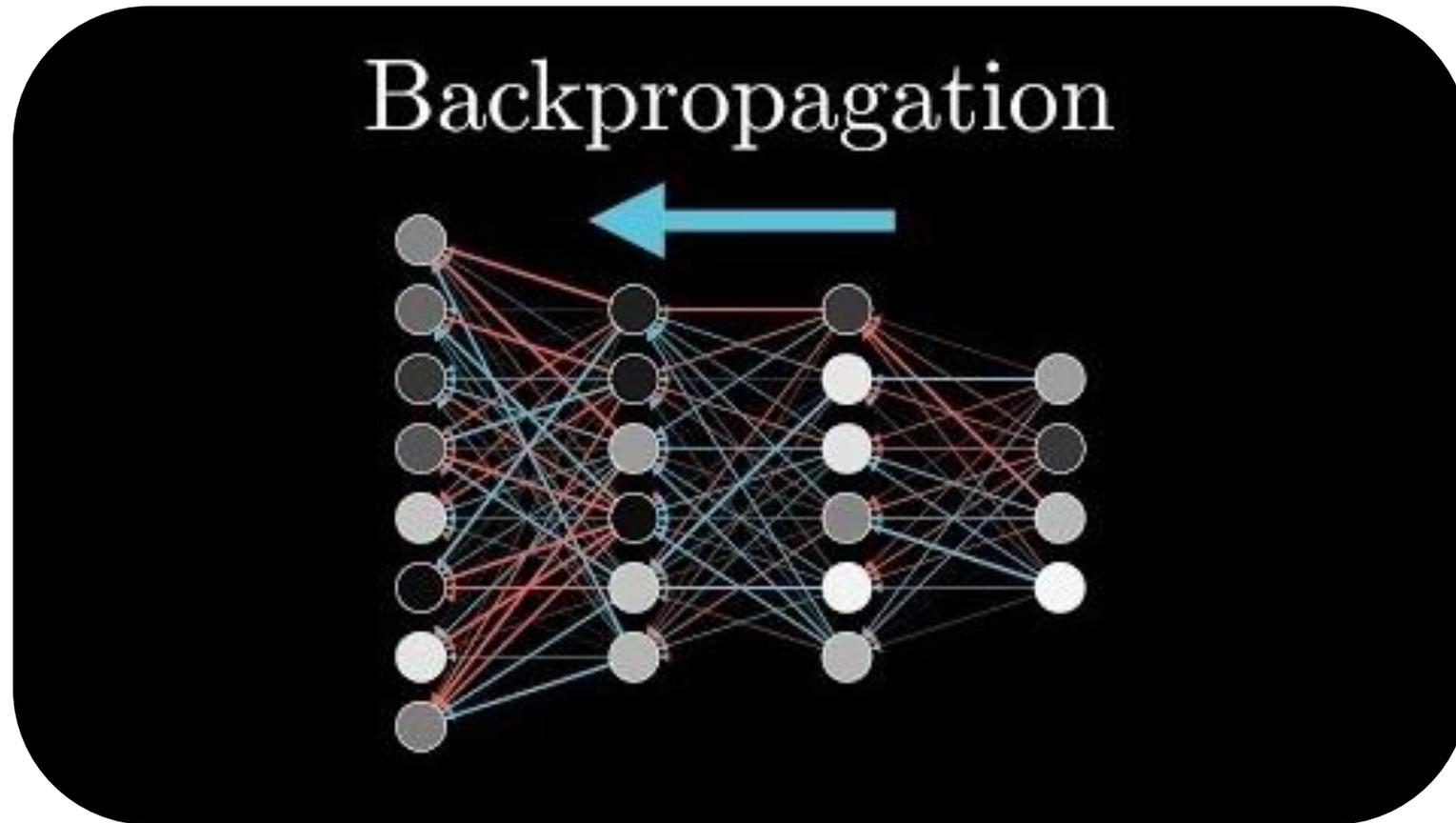


Backpropagation: Efficiently Computing the Gradients

- An efficient way of **computing gradients** using chain rule
- The reason why we want **everything to be differentiable** in deep learning

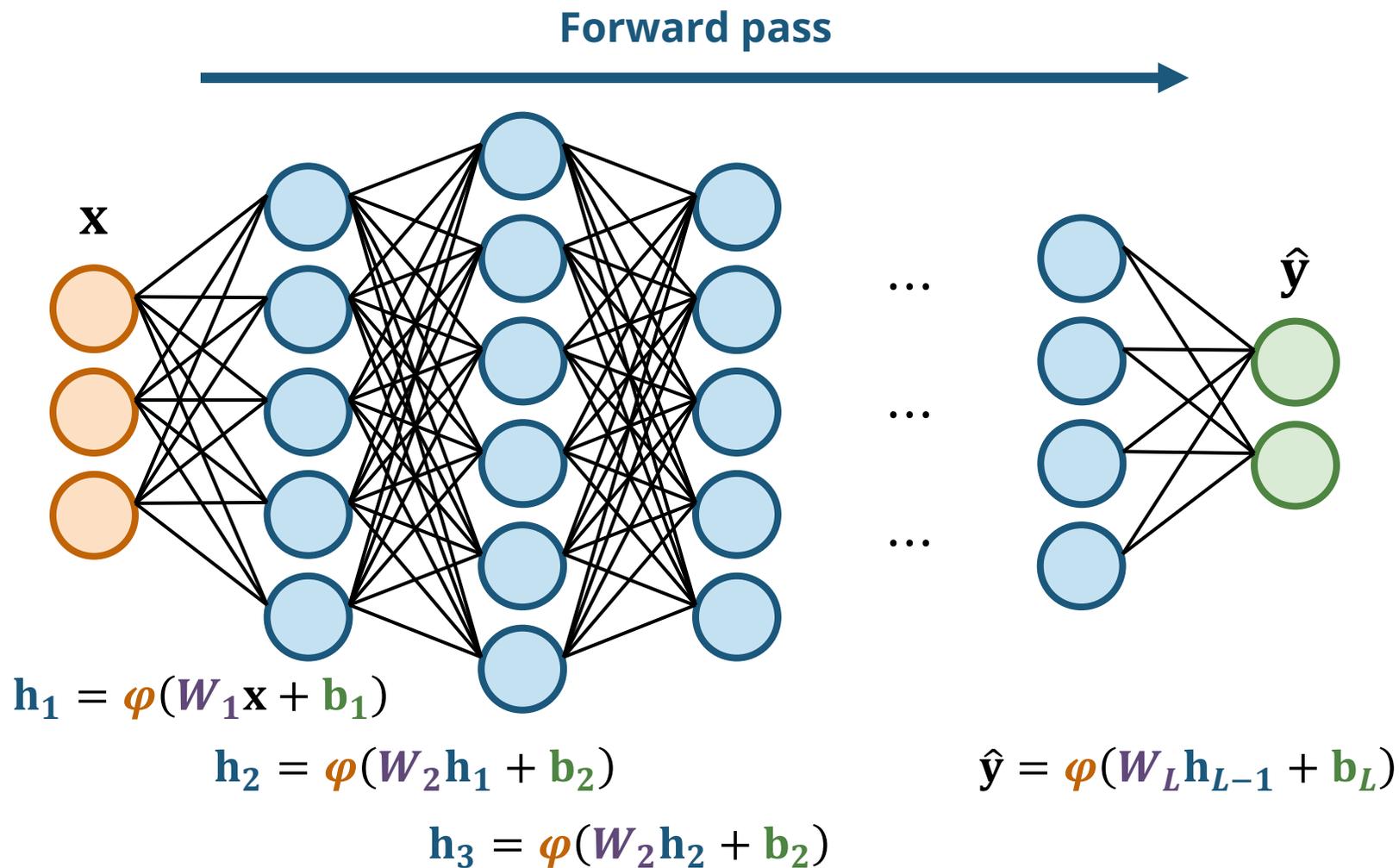
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Backpropagation: Efficiently Computing the Gradients

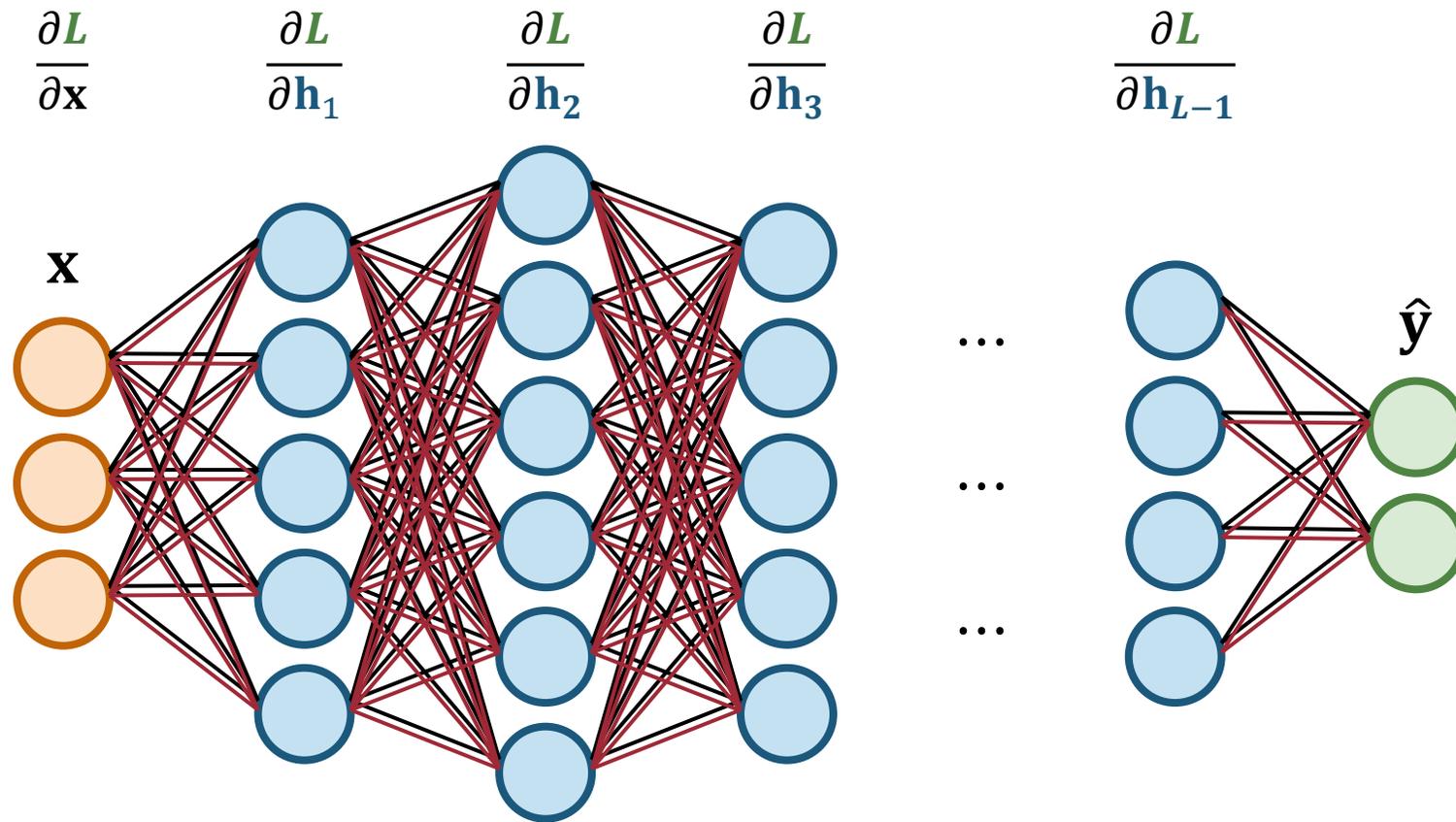


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Forward Pass & Backward Pass



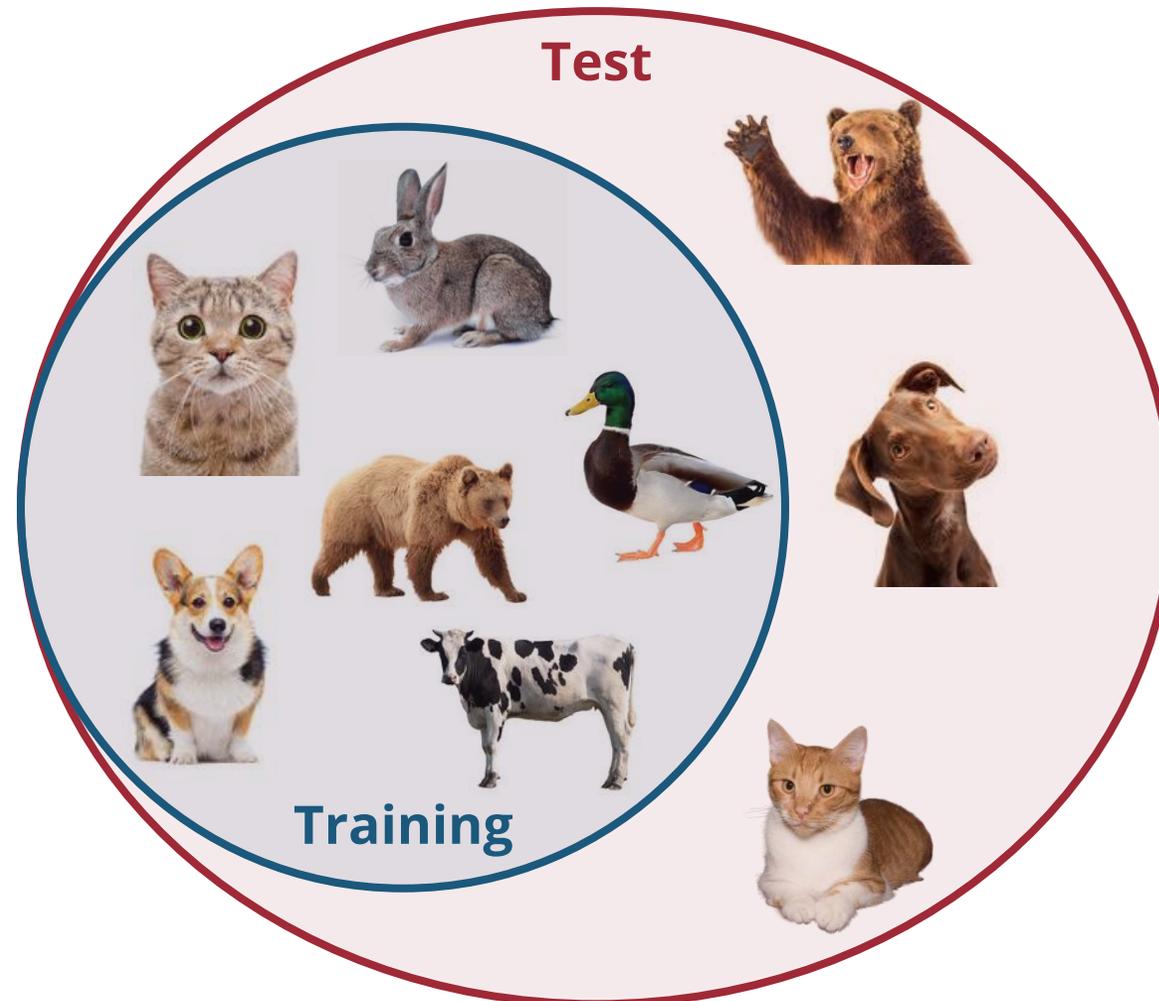
Forward Pass & Backward Pass



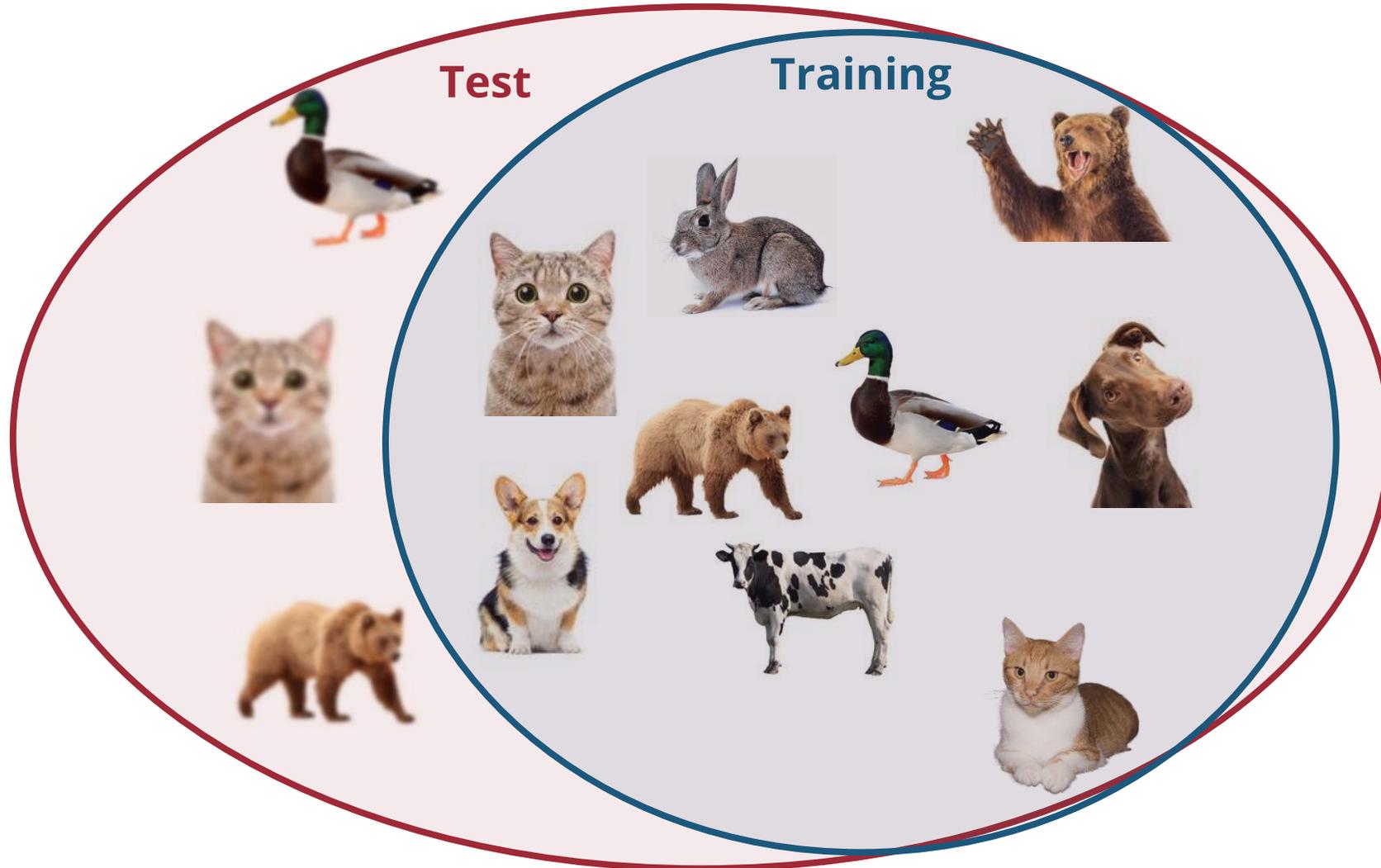
Backward pass
`loss.backward()`

Training-Validation-Test

In-distribution vs Out-of-distribution



In-distribution vs Out-of-distribution



In-distribution vs Out-of-distribution



In-distribution vs Out-of-distribution

- **Key:** Make the training distribution **closer to** the target distribution
- First, we need to **define our target distribution**
- Then, we can try to
 - Collect a **diverse** dataset covering that covers different parts of the target distribution
 - Apply **data augmentation** to fill the gaps in the distribution

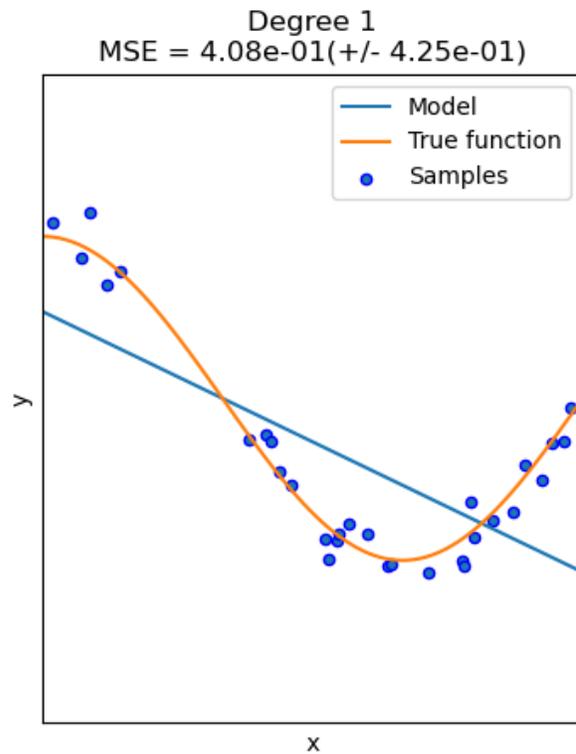
In-distribution vs Out-of-distribution

- What do we really want?
 - Good performance on the **training samples** **We already have their answers**
 - Good performance on **unseen samples in the target distribution** **Yep, we can do this!**
 - Good performance on **out-of-distribution samples** **Hopefully, but not guaranteed**

**How to achieve good performance on
unseen samples in the target distribution**

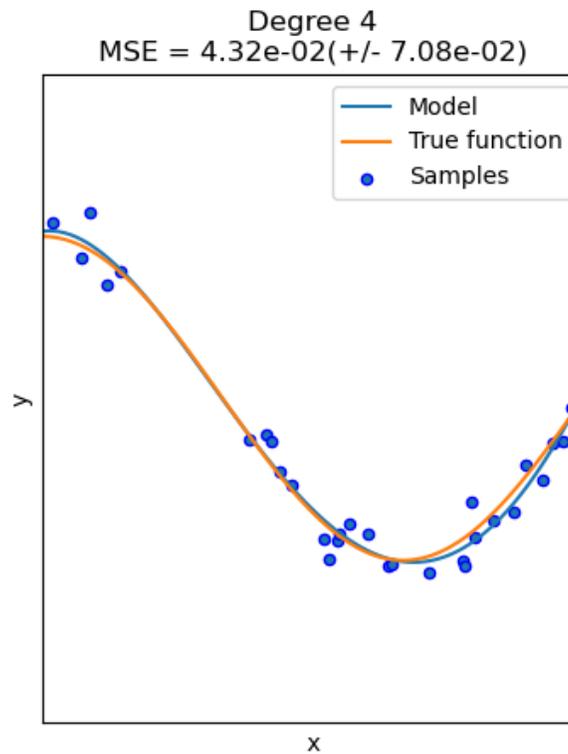
Overfitting & Underfitting

Underfitting

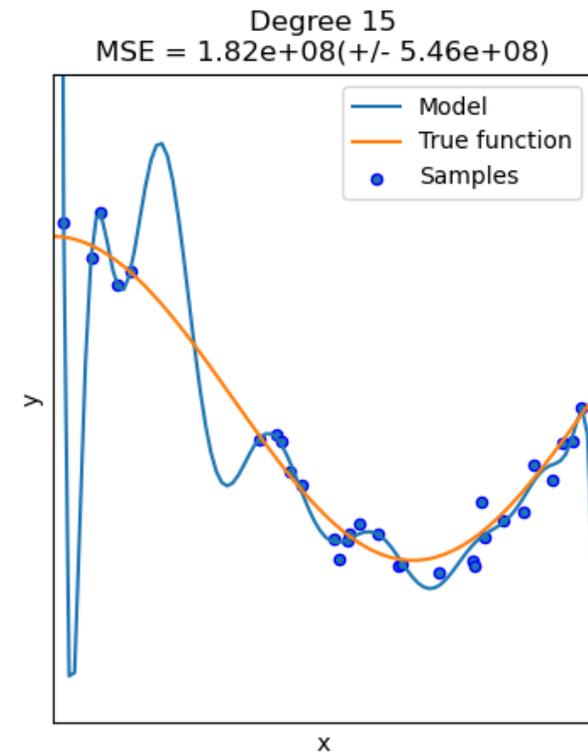


Model too **inexpressive**

Good fit!



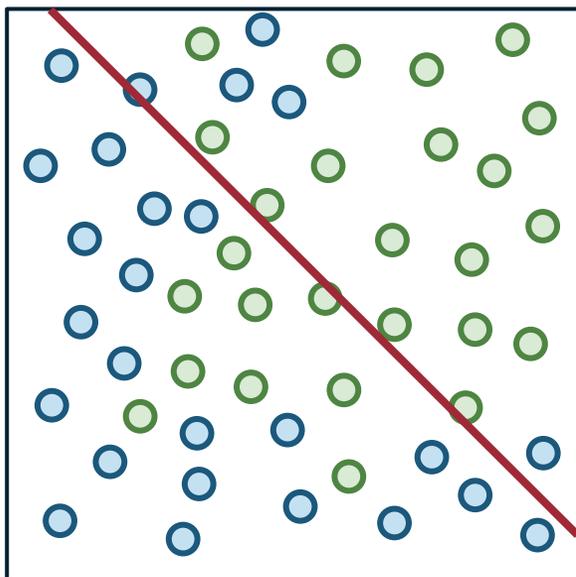
Overfitting



Model too **expressive**

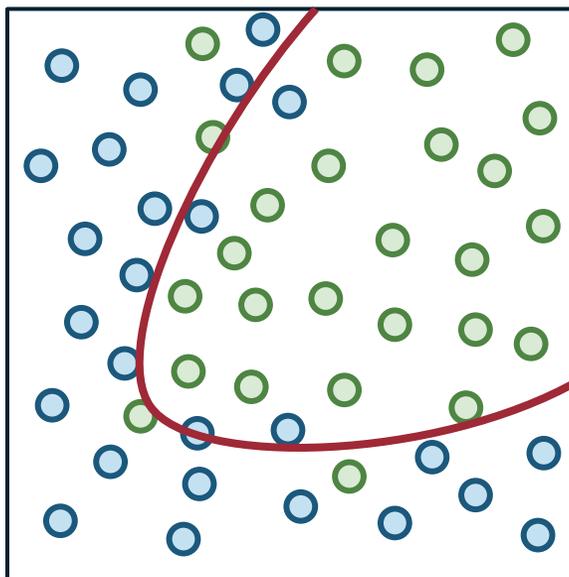
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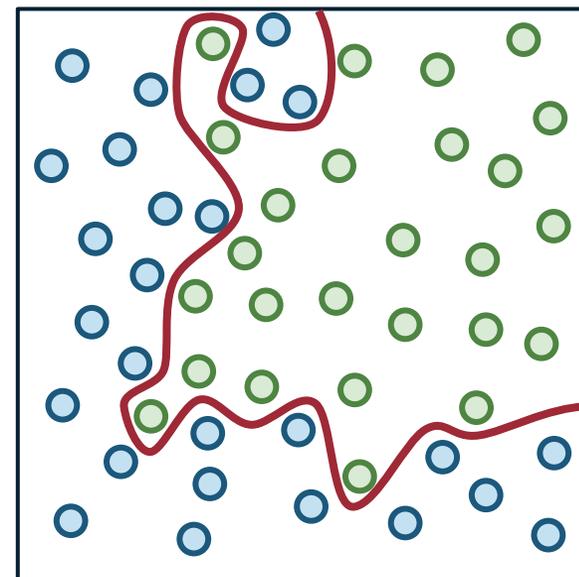


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Overfitting



Model too **expressive**

Train-Test Split

- **Goal:** Good performance on **unseen samples in the target distribution**



Train-Test Split

- **Goal:** Good performance on **unseen samples in the target distribution**

Training



Test



Test Set is an Estimation of the Test Distribution

- We create a test set because we want to **estimate the performance when the model is applied to an interested distribution**

Train-Validation-Test Split

Training



Test



Train-Validation-Test Split

Training



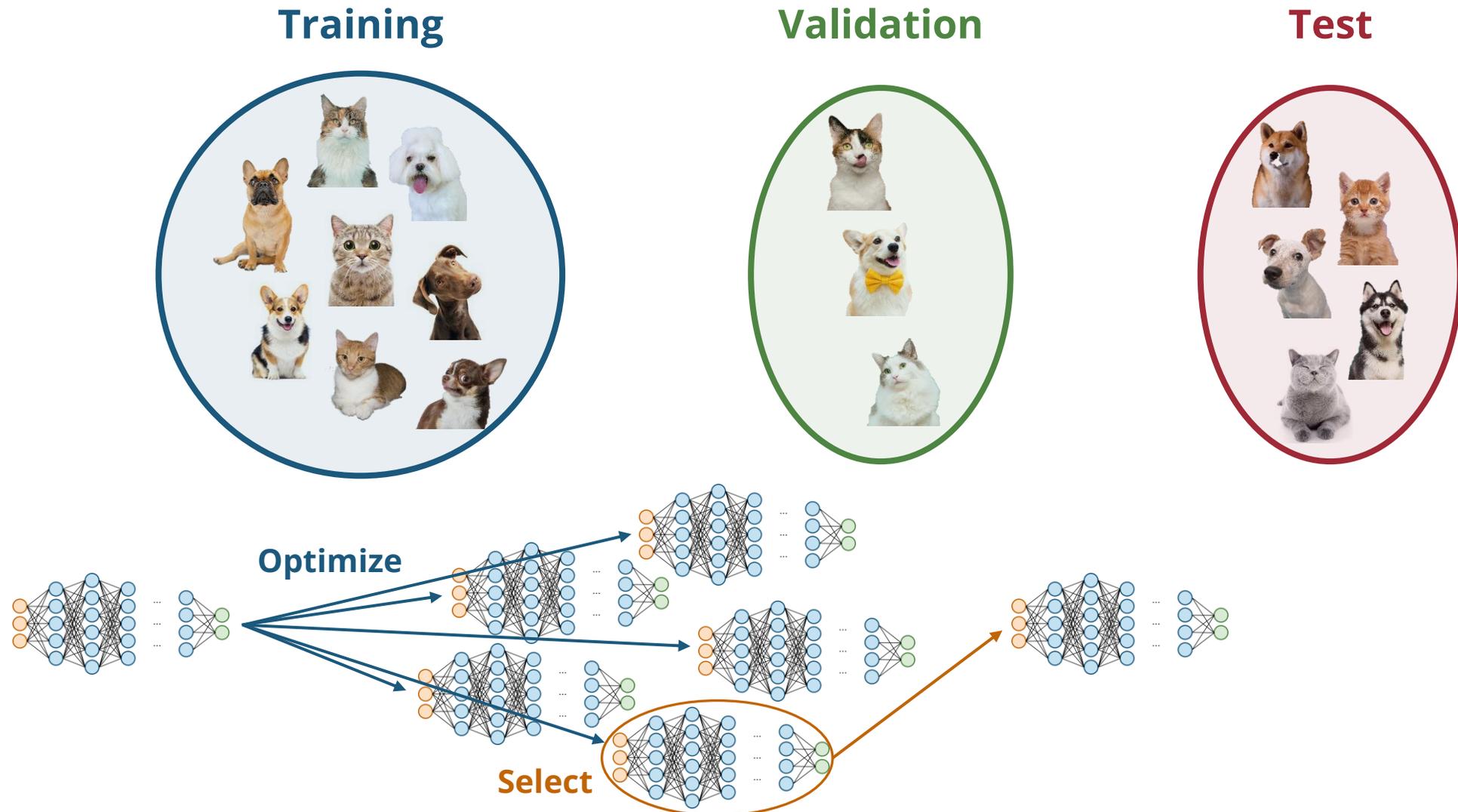
Validation



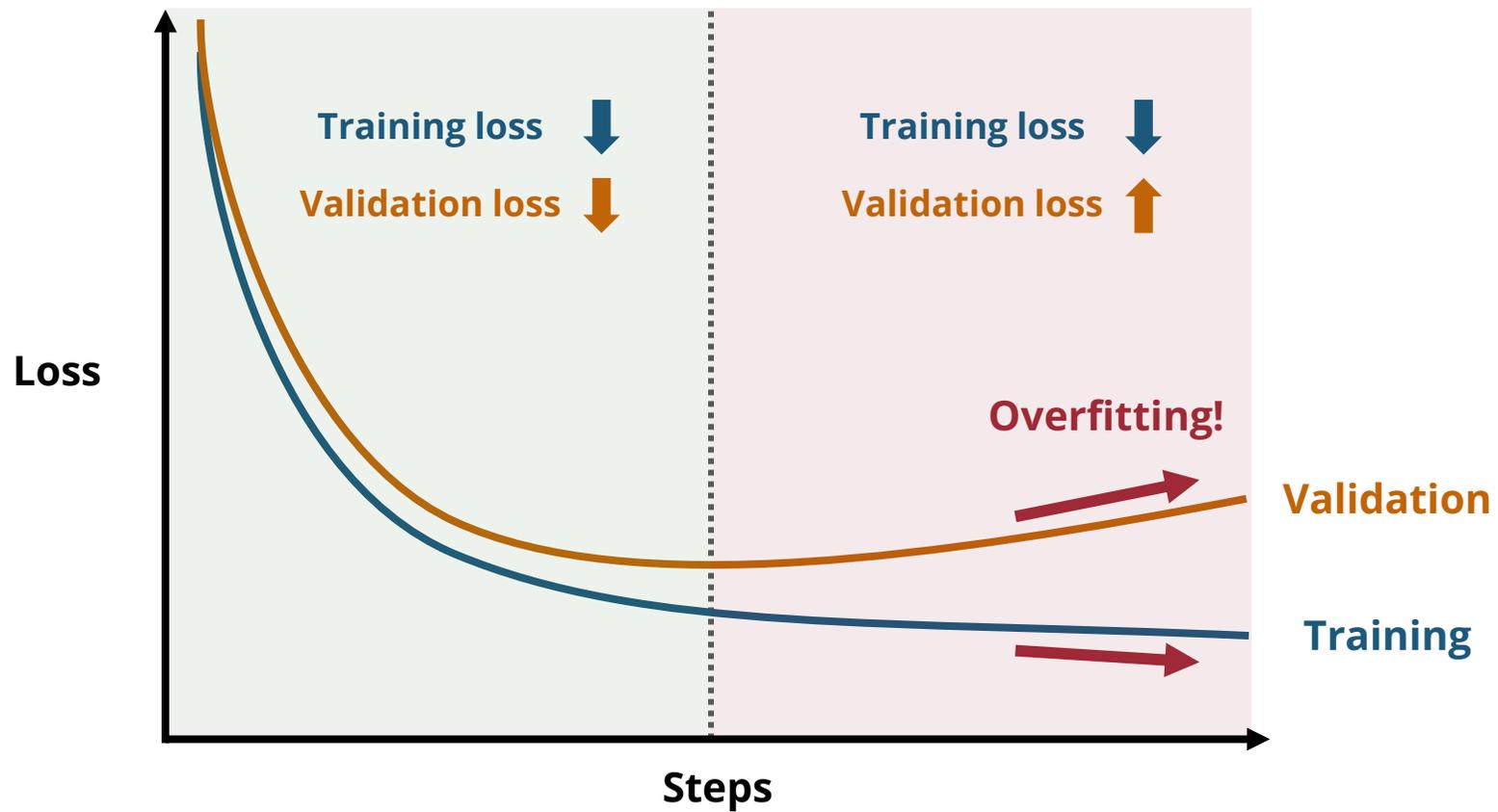
Test



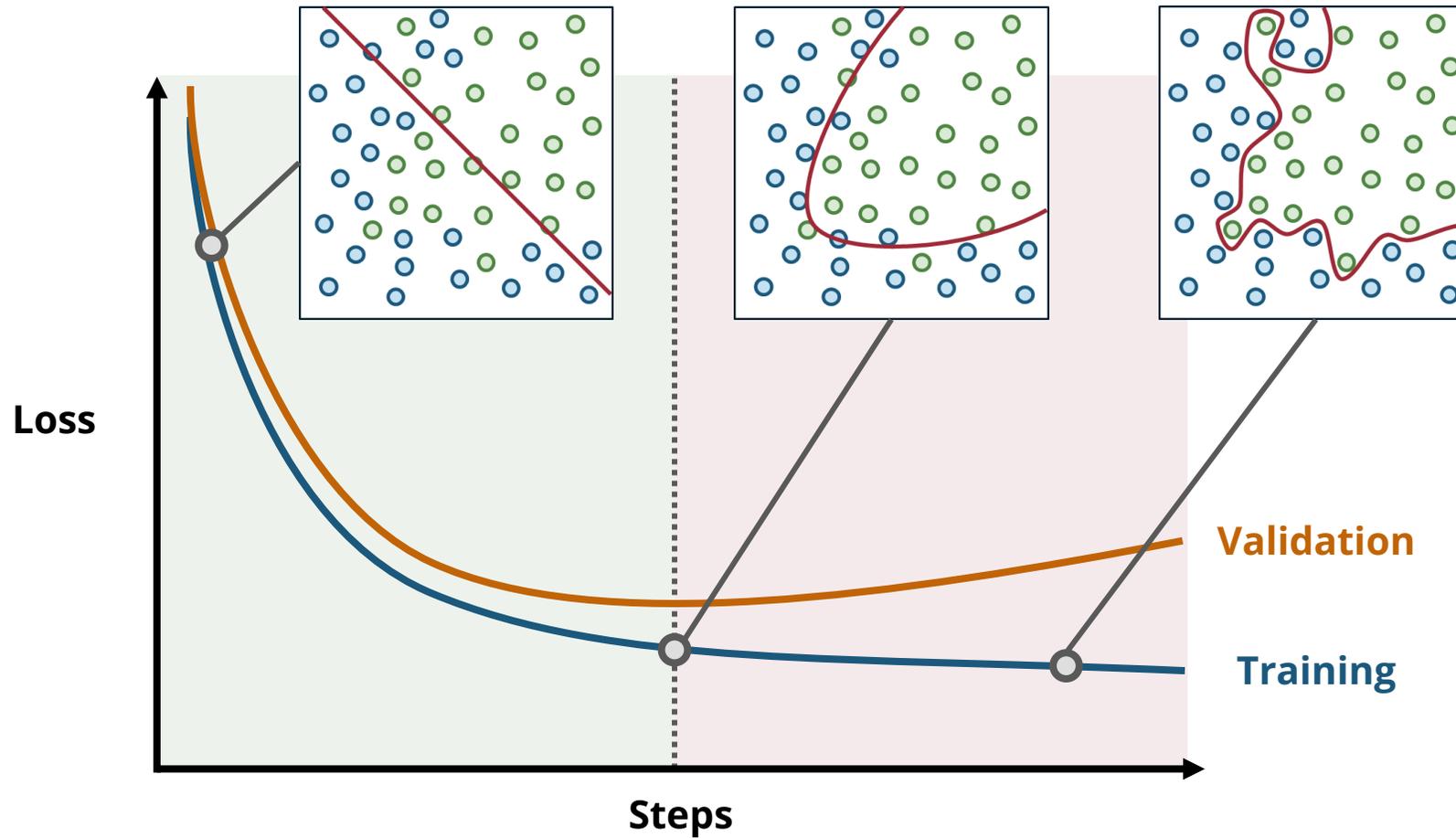
Training-Validation-Test Pipeline



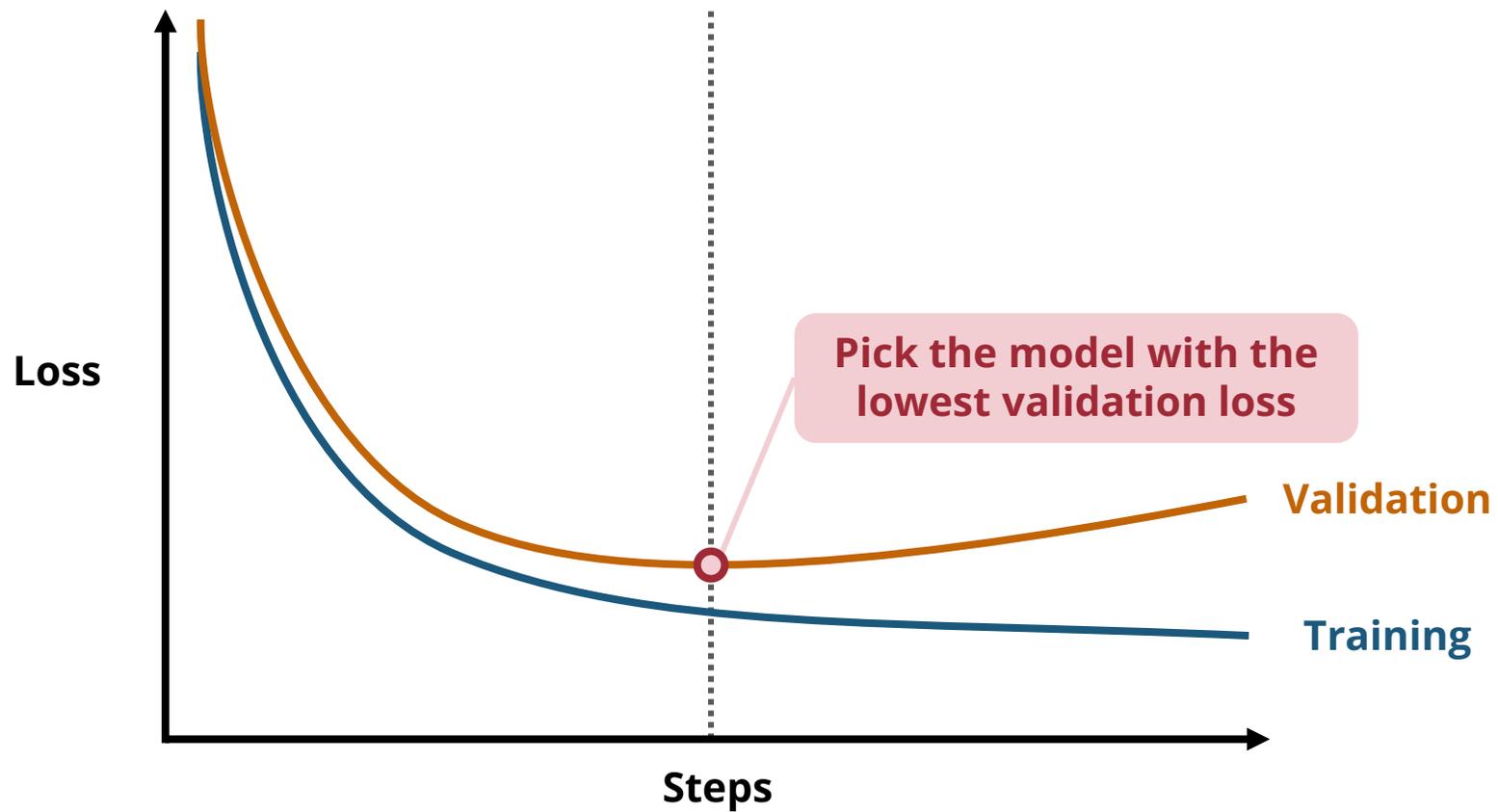
Training vs Validation Losses



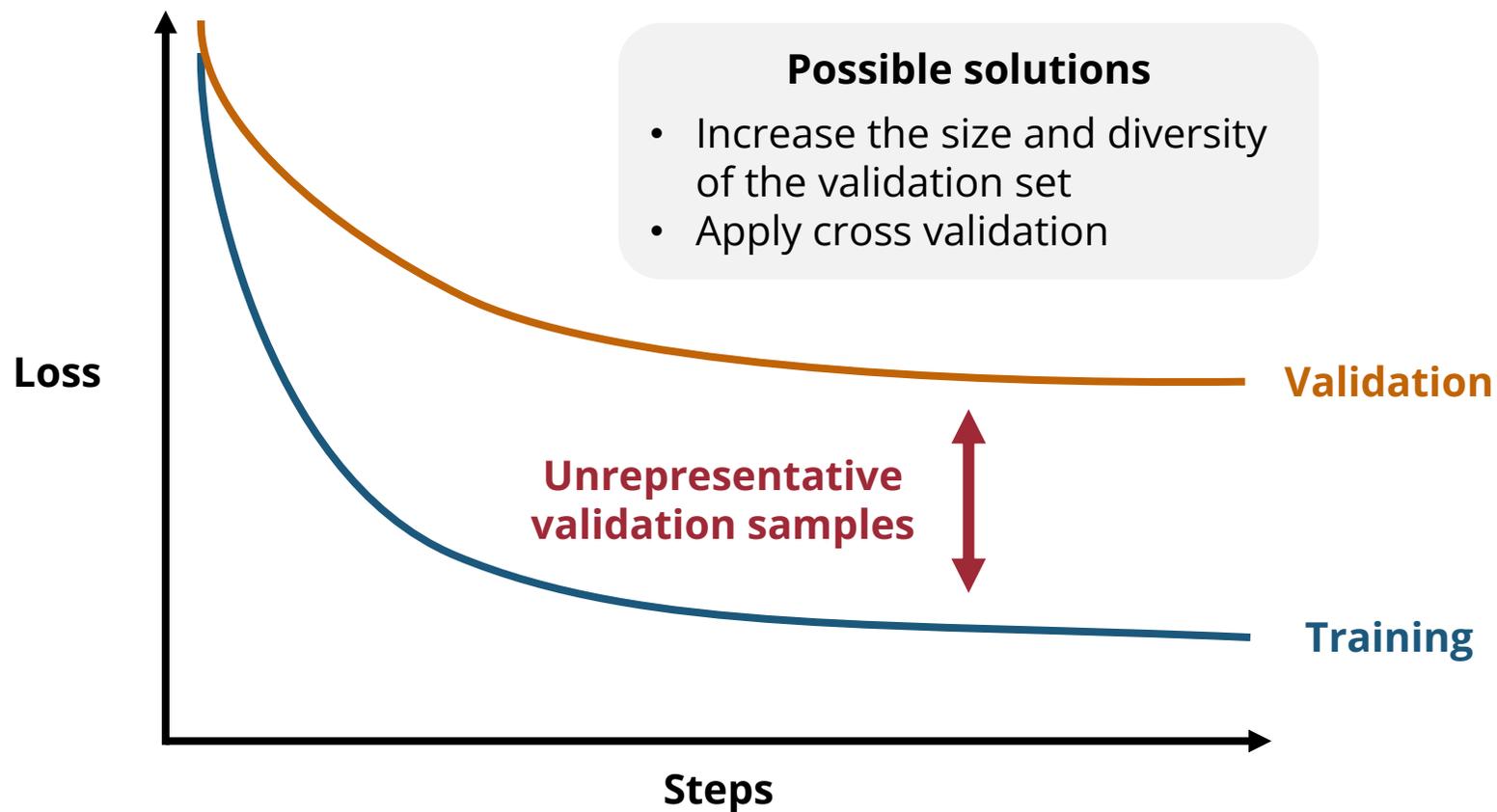
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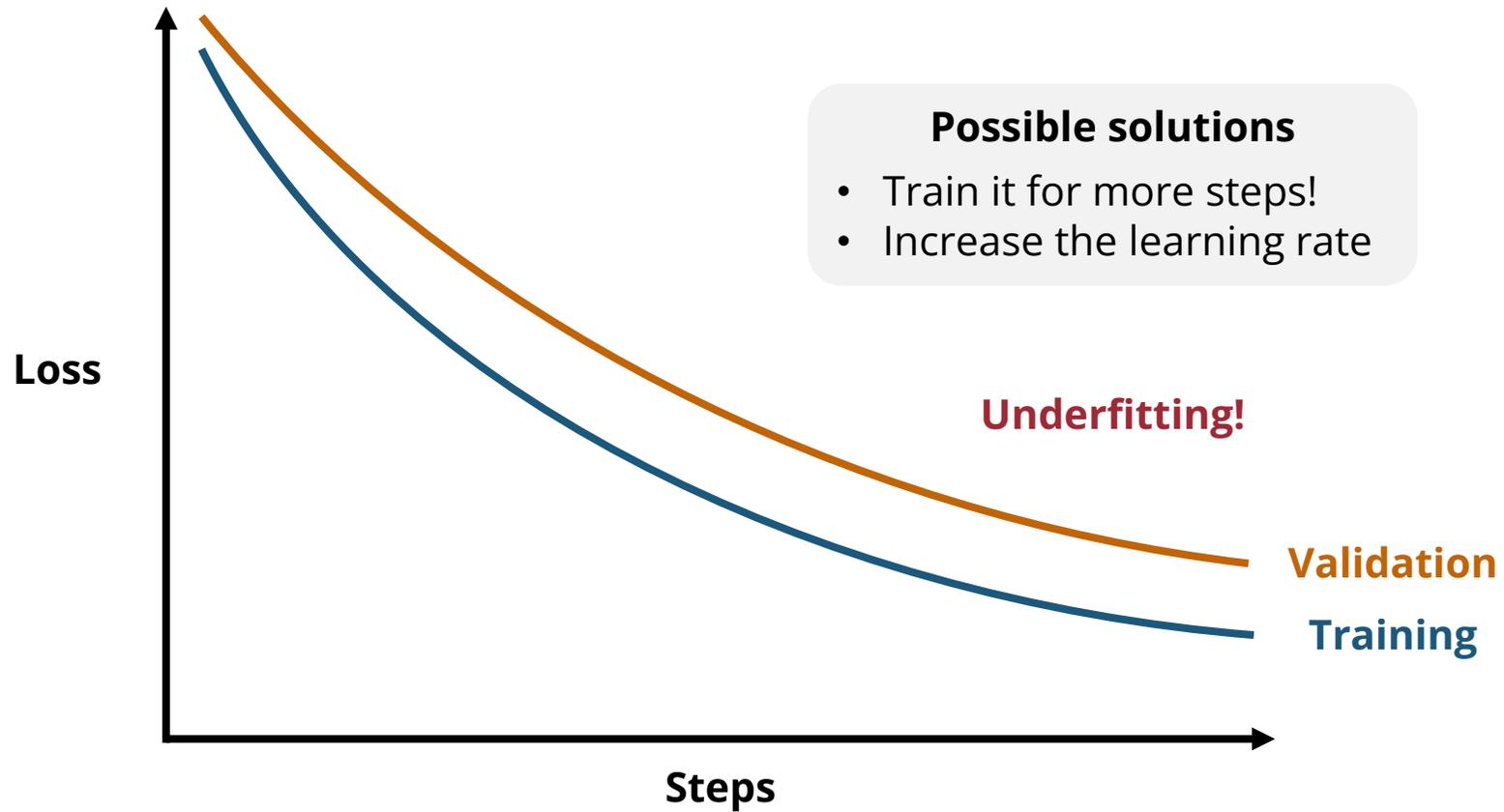
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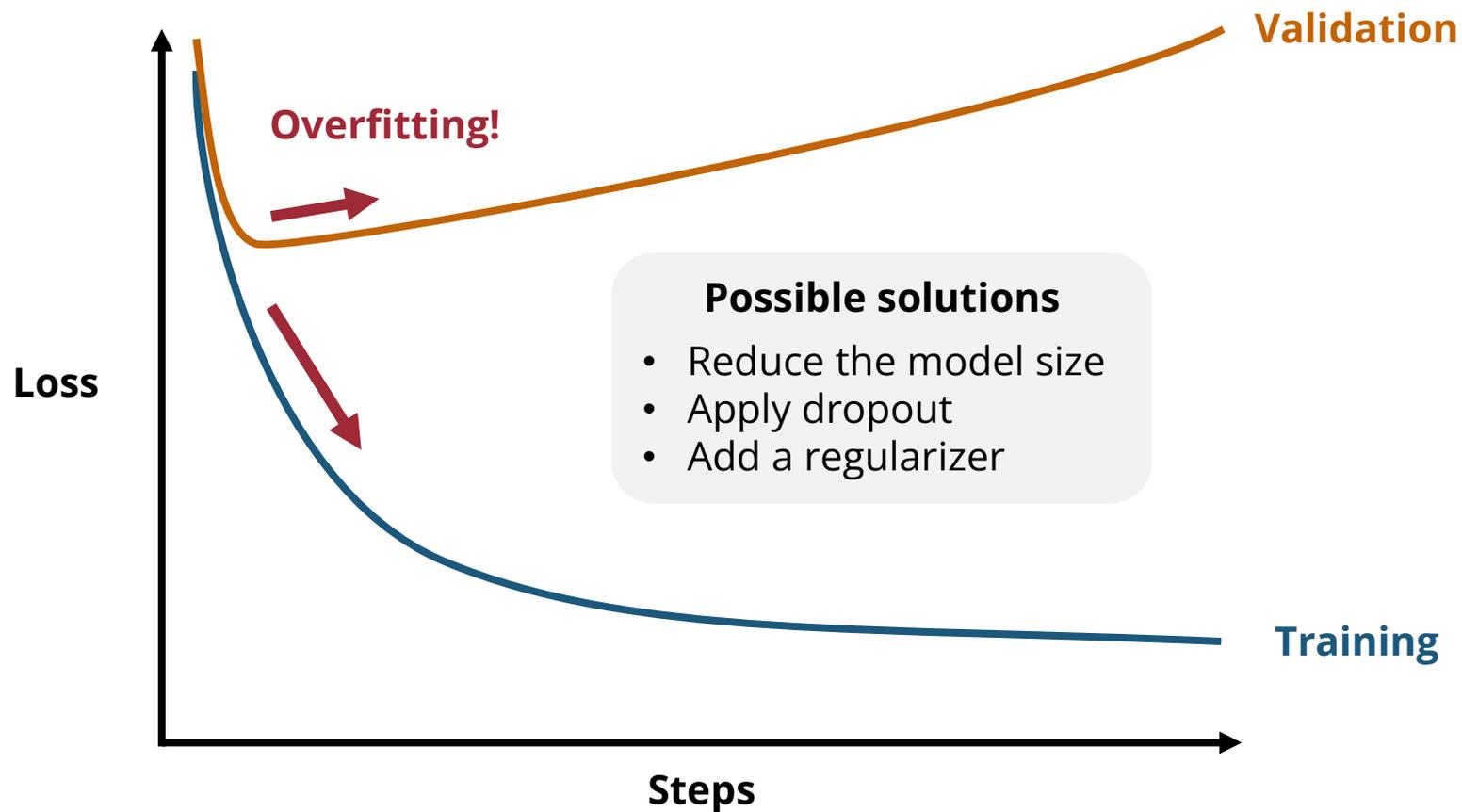
Training vs Validation Losses



Training vs Validation Losses



Training vs Validation Losses



Train-Validation-Test Split

- **Keys**

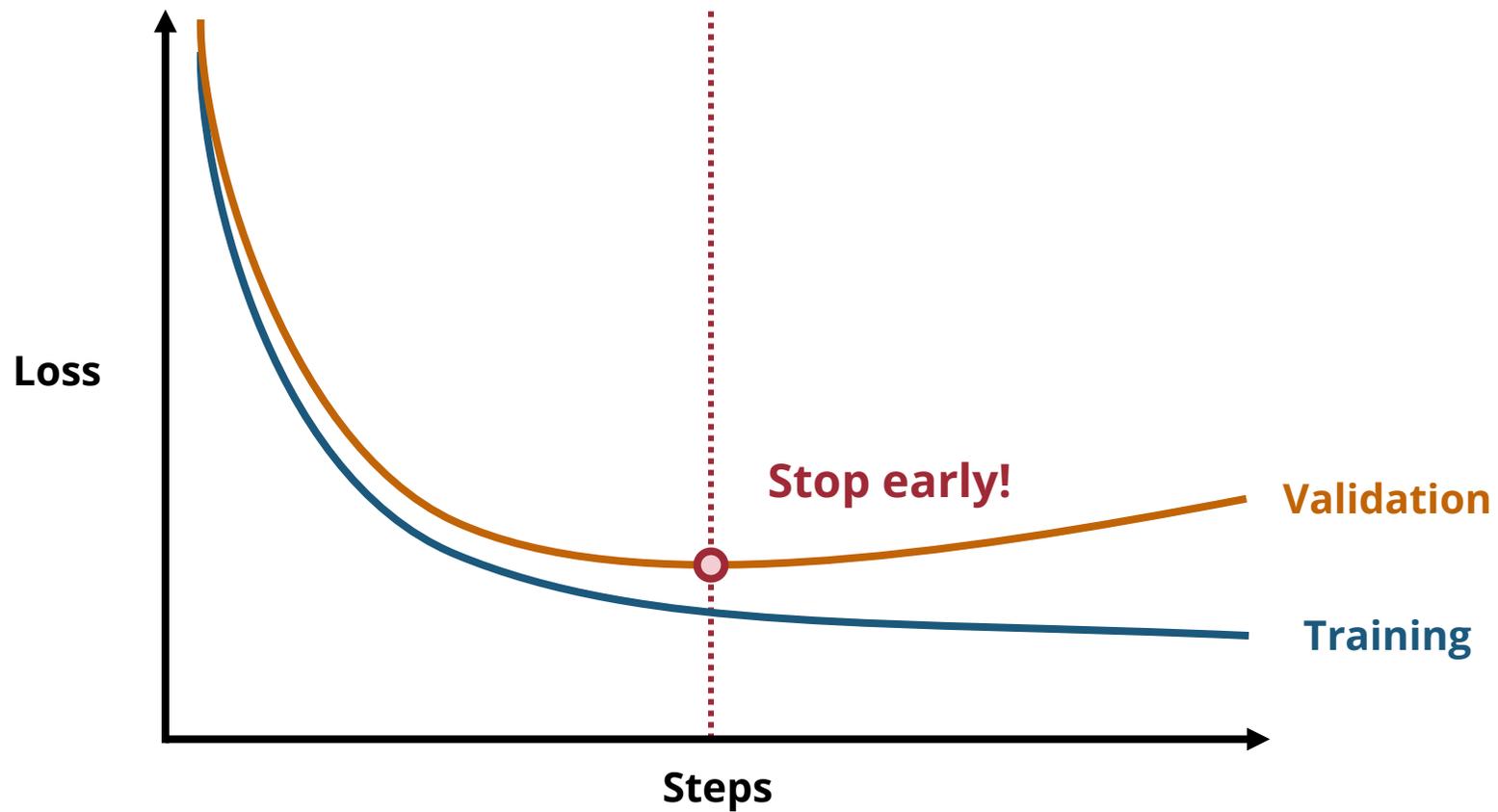
- **Never train or select your model on test samples!**
- Don't over-select your model on the validation set

- What's the **best ratio**?

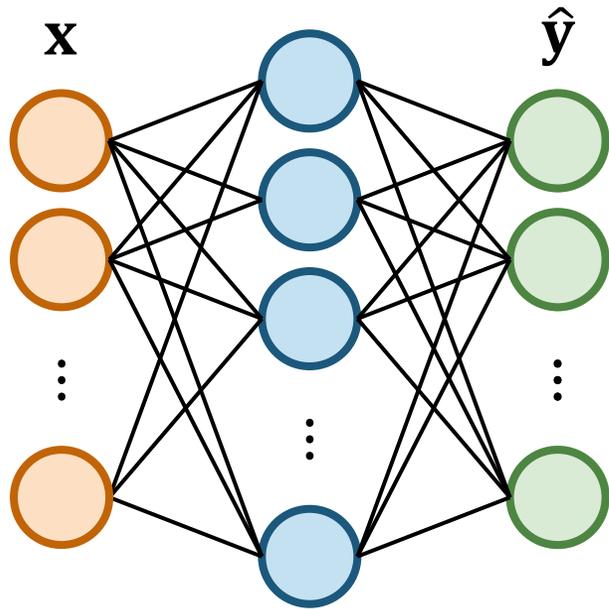
- Most common: **8:1:1** or 9:0.5:0.5
- For smaller dataset, you might even want 6:2:2

Overcoming Overfitting

Early Stopping

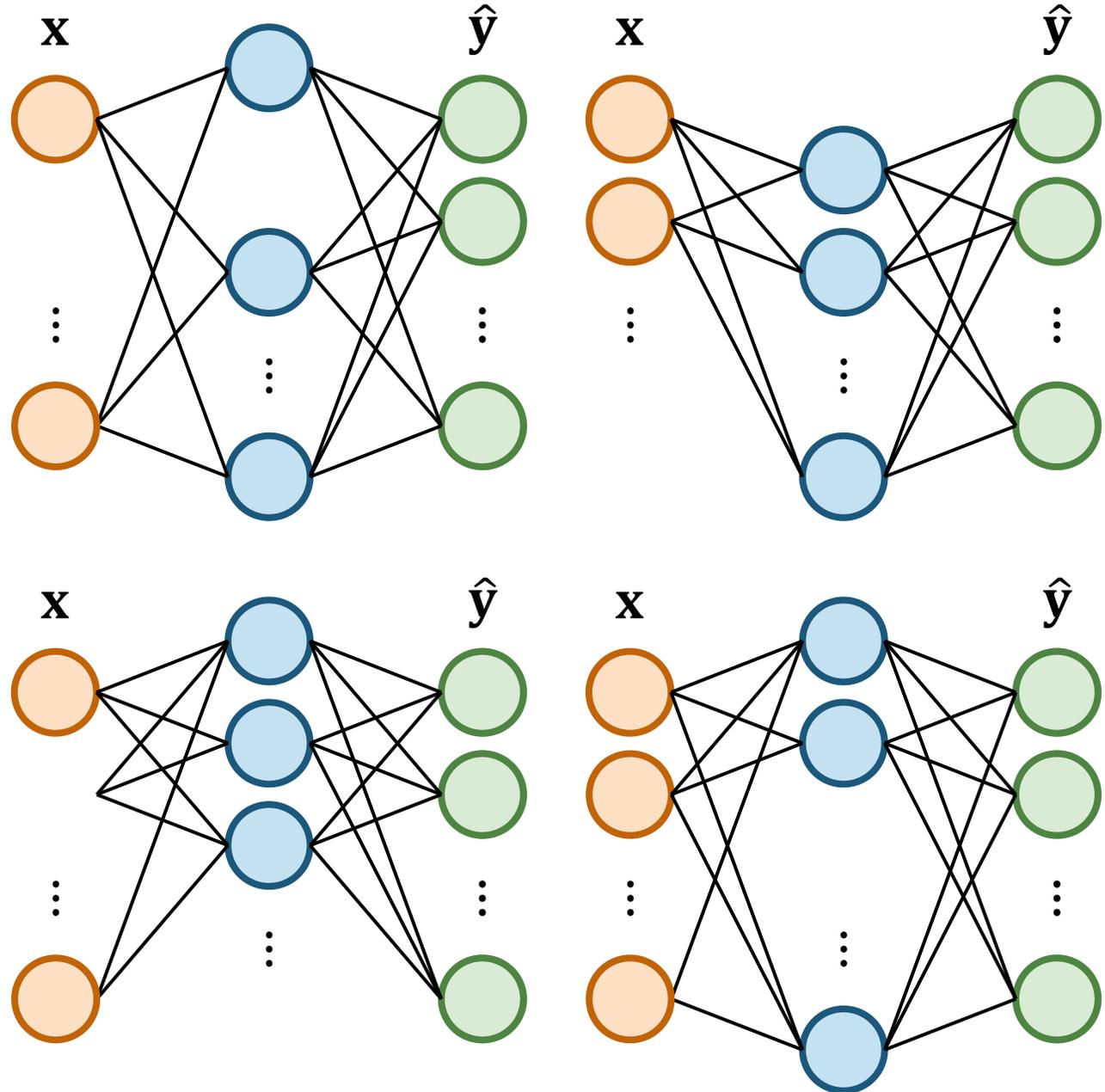


Dropout

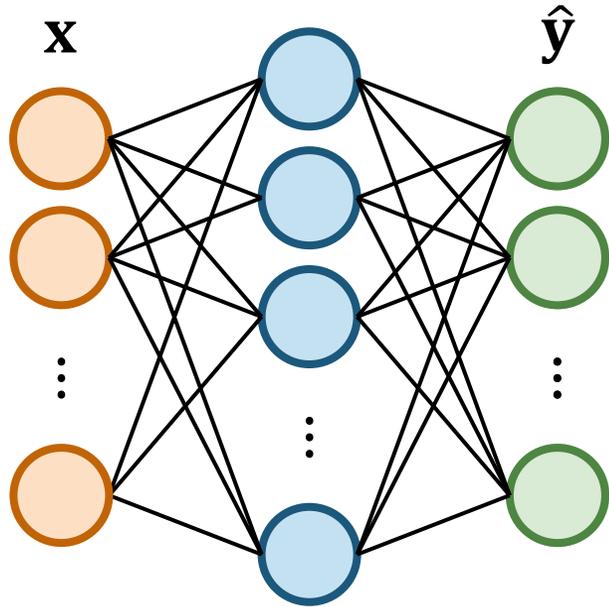


Each neuron may be removed with probability p during training

Dropout rate

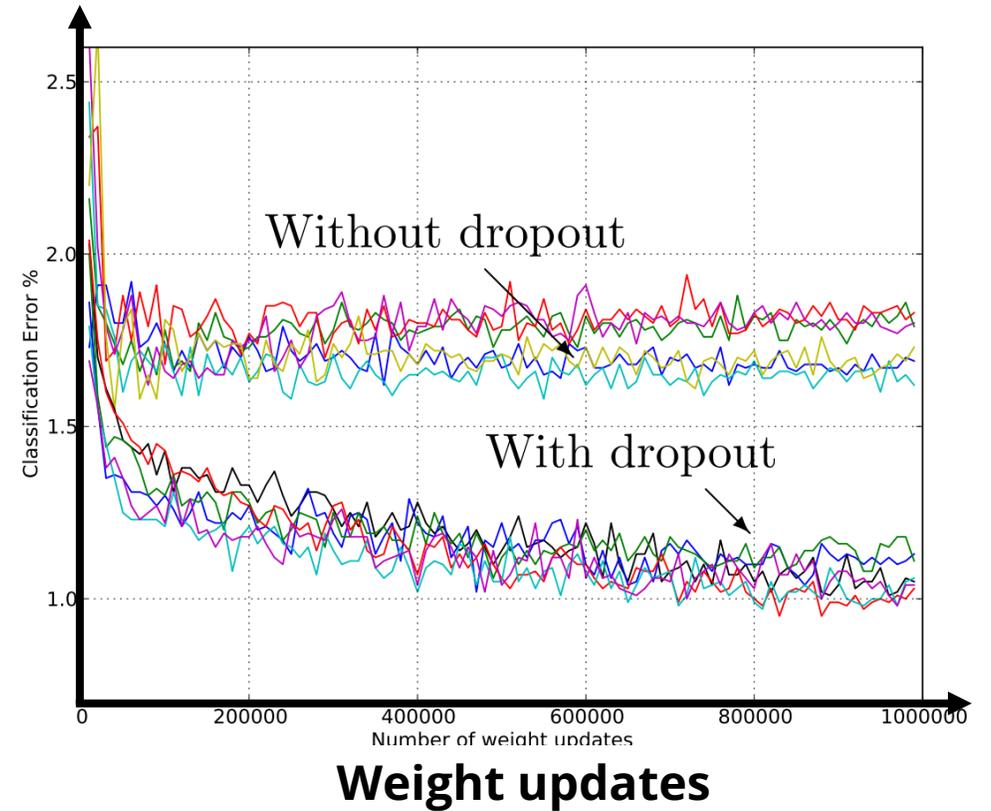


Dropout



Each neuron may be removed with probability p during training

Test error rate



Regularization Term

- A regularization term can help alleviate overfitting
 - **L1 regularization** (LASSO)

$$L' = L + \lambda(|w_1| + |w_2| + \dots + |w_K|)$$

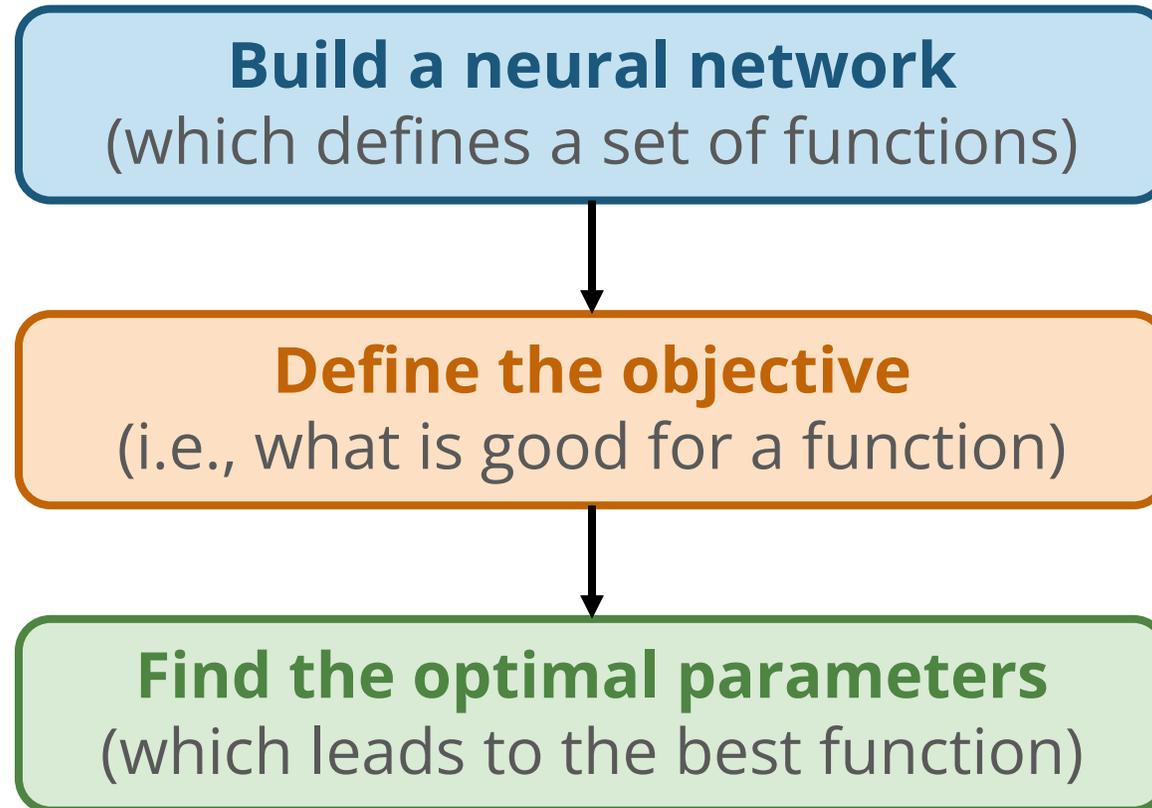
- **L2 regularization** (ridge regression)

$$L' = L + \lambda(w_1^2 + w_2^2 + \dots + w_K^2)$$

Both L1 and L2 regularizations encourage smaller weights

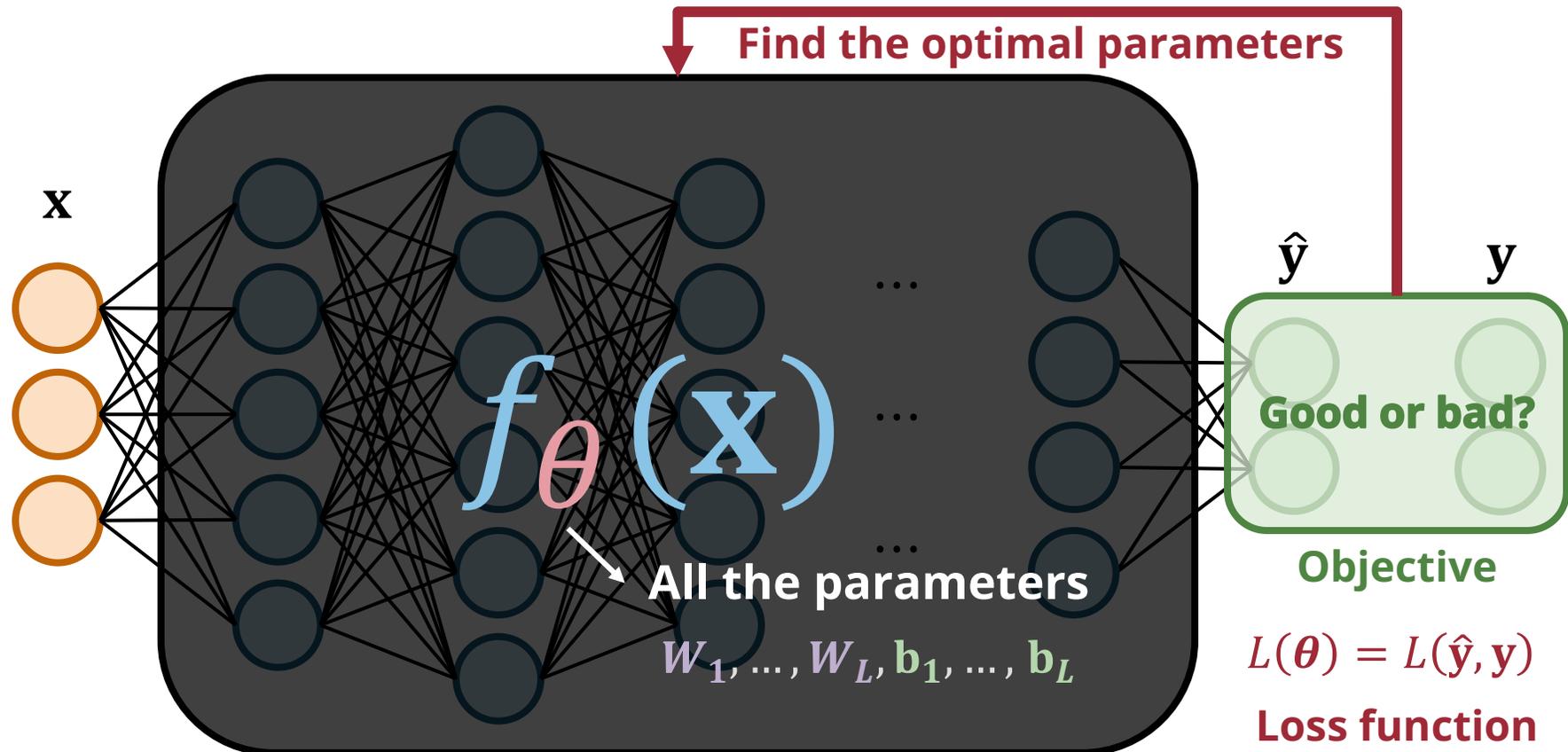
Recap

| Training a Neural Network



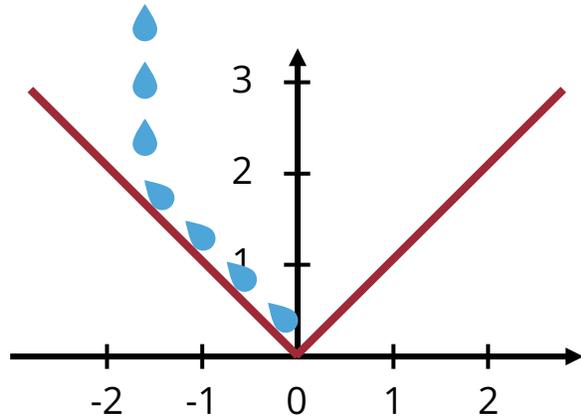
Neural Networks are Parameterized Functions

- A neural network represents **a set of functions**



L1 vs L2 Losses

L1 loss

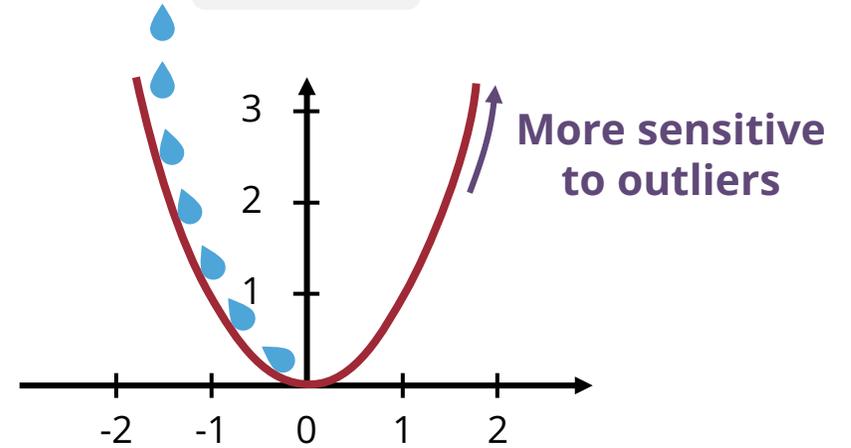


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$$L(\hat{\mathbf{y}}, \mathbf{y}) = \mathbf{MAE}(\hat{\mathbf{y}}, \mathbf{y}) = \frac{1}{n} \sum_{i=1}^n |\hat{y}_i - y_i|$$

Mean Absolute Error (MAE)

L2 loss

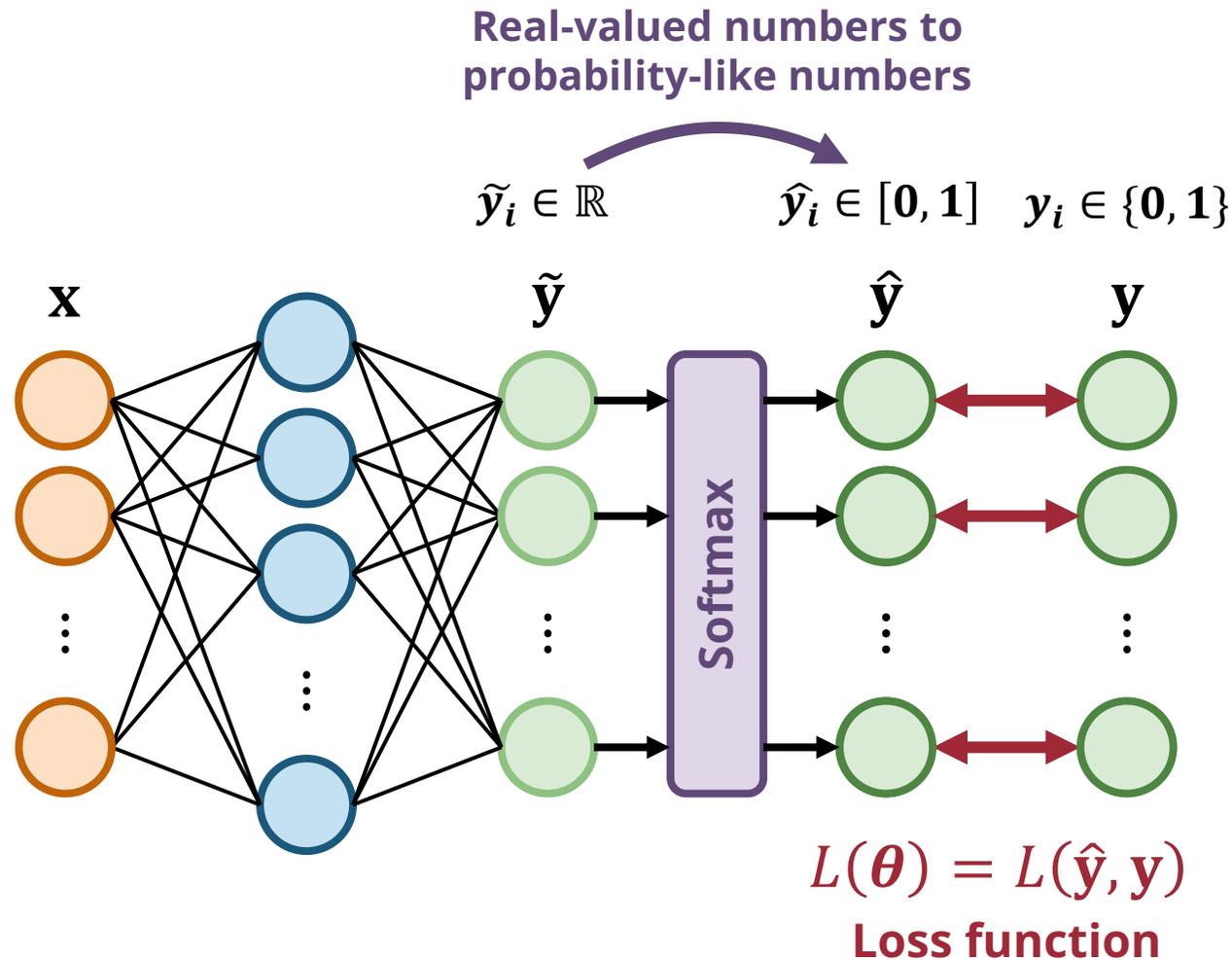


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Mean Squared Error (MSE)

Cross Entropy for Multiclass Classification



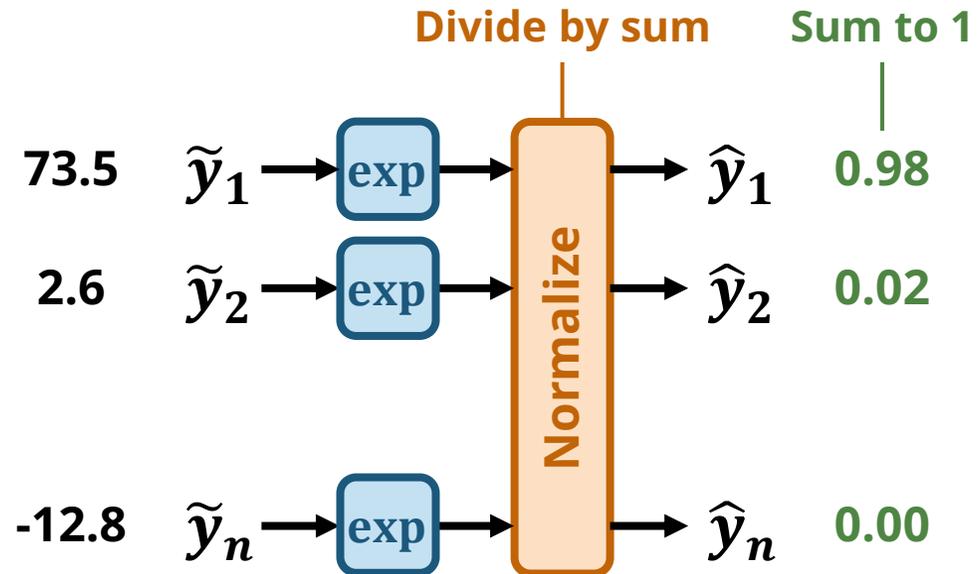
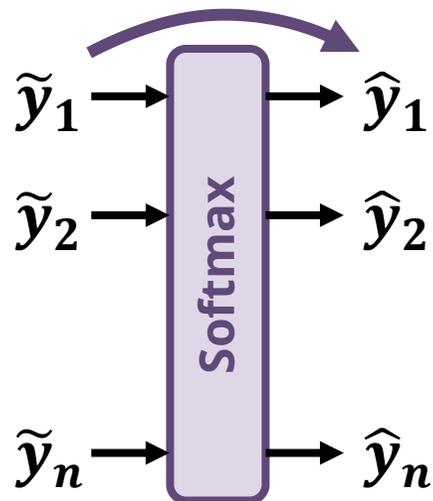
Softmax

$$\hat{y}_i = \frac{e^{\tilde{y}_i}}{\sum_{j=1}^n e^{\tilde{y}_j}}$$

Softmax

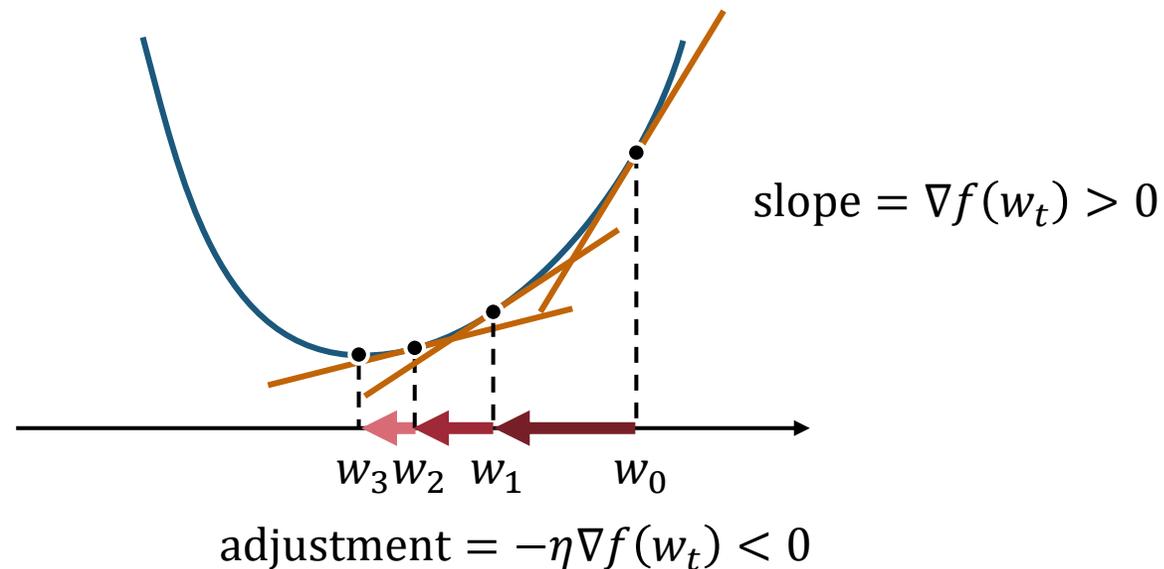
- **Intuition:** Map several numbers to $[0, 1]$ while **keeping their relative magnitude**
 - Softmax is like the **multivariate version of sigmoid**

Real-valued numbers to probability-like numbers

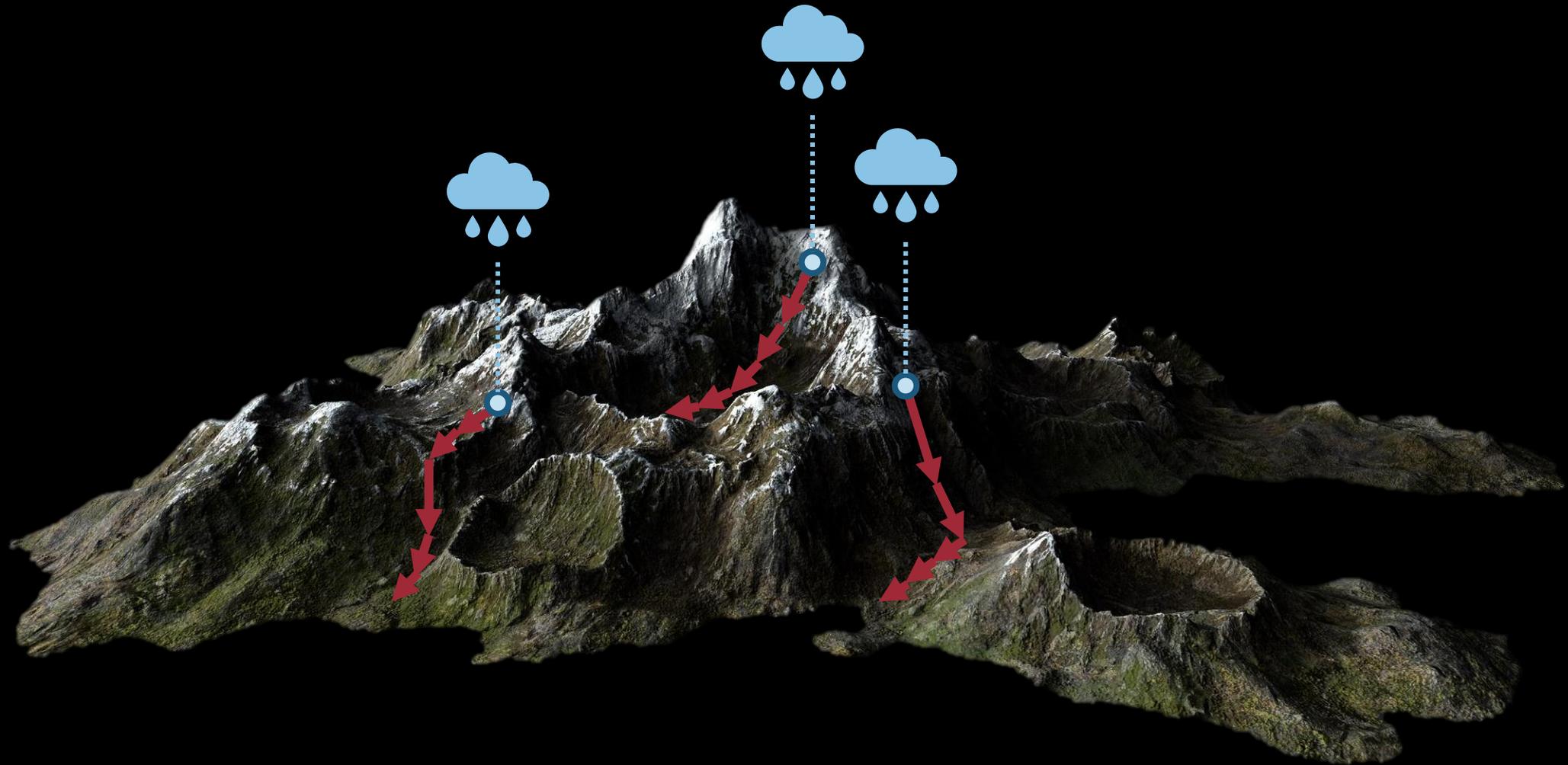


Gradient Descent: Pseudocode

- Pick an initial weight vector w_0 and learning rate η
- Repeat until convergence: $w_{t+1} = w_t - \eta \nabla f(w_t)$



Gradient Descent: 3D Case

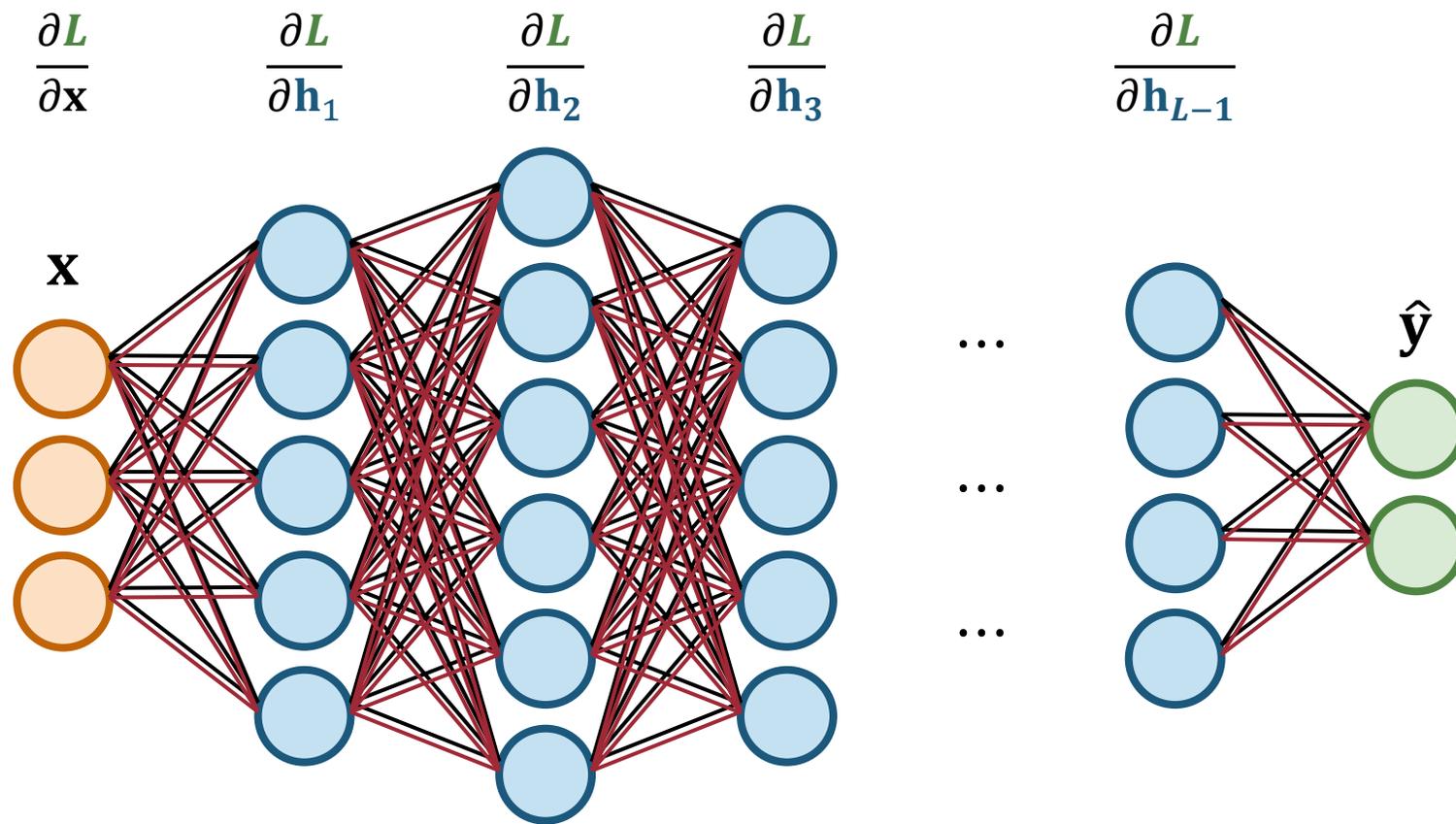


Backpropagation: Efficiently Computing the Gradients

- An efficient way of **computing gradients** using chain rule
- The reason why we want **everything to be differentiable** in deep learning

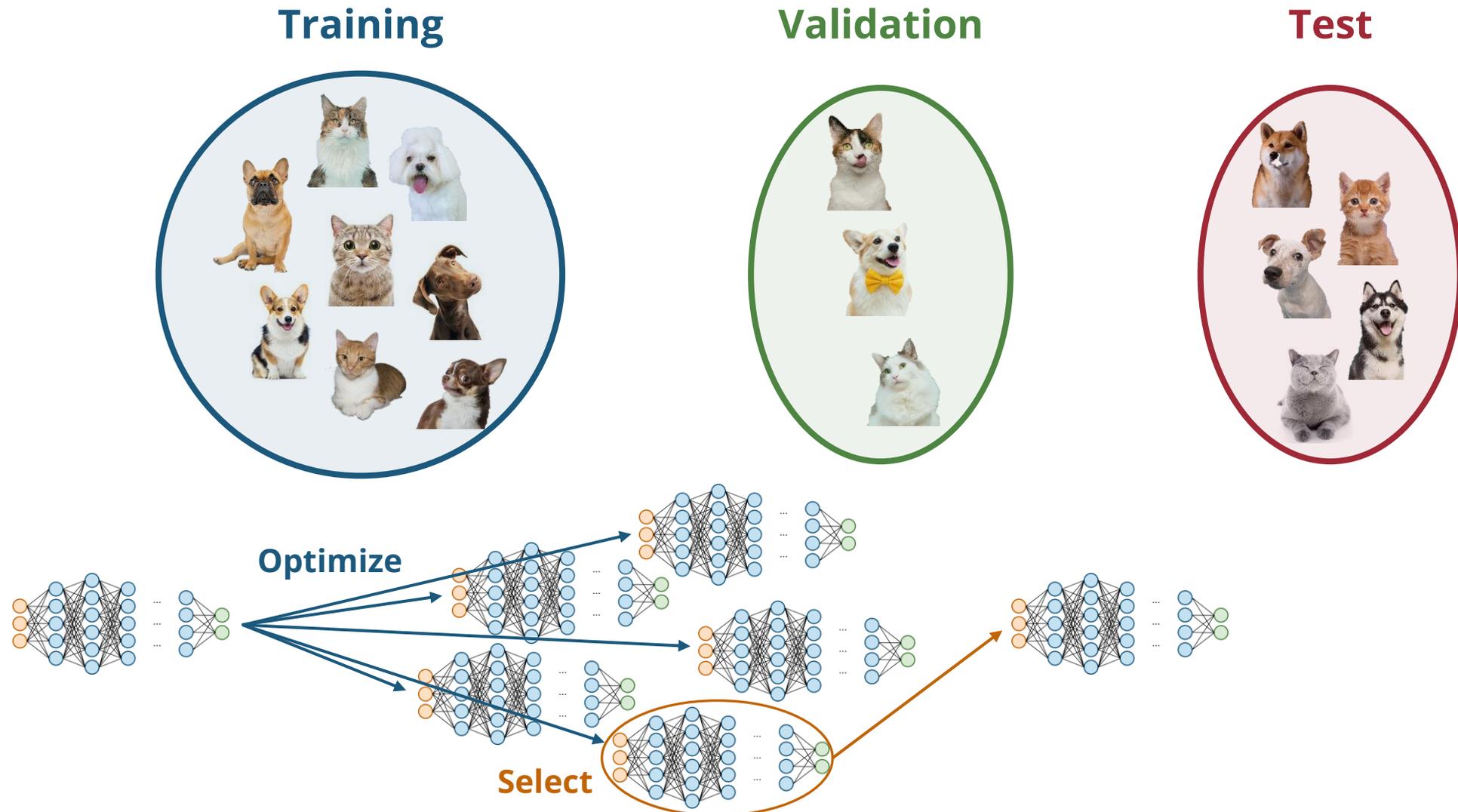
$$w_{t+1} = w_t - \eta \nabla f(w_t)$$

Forward Pass & Backward Pass

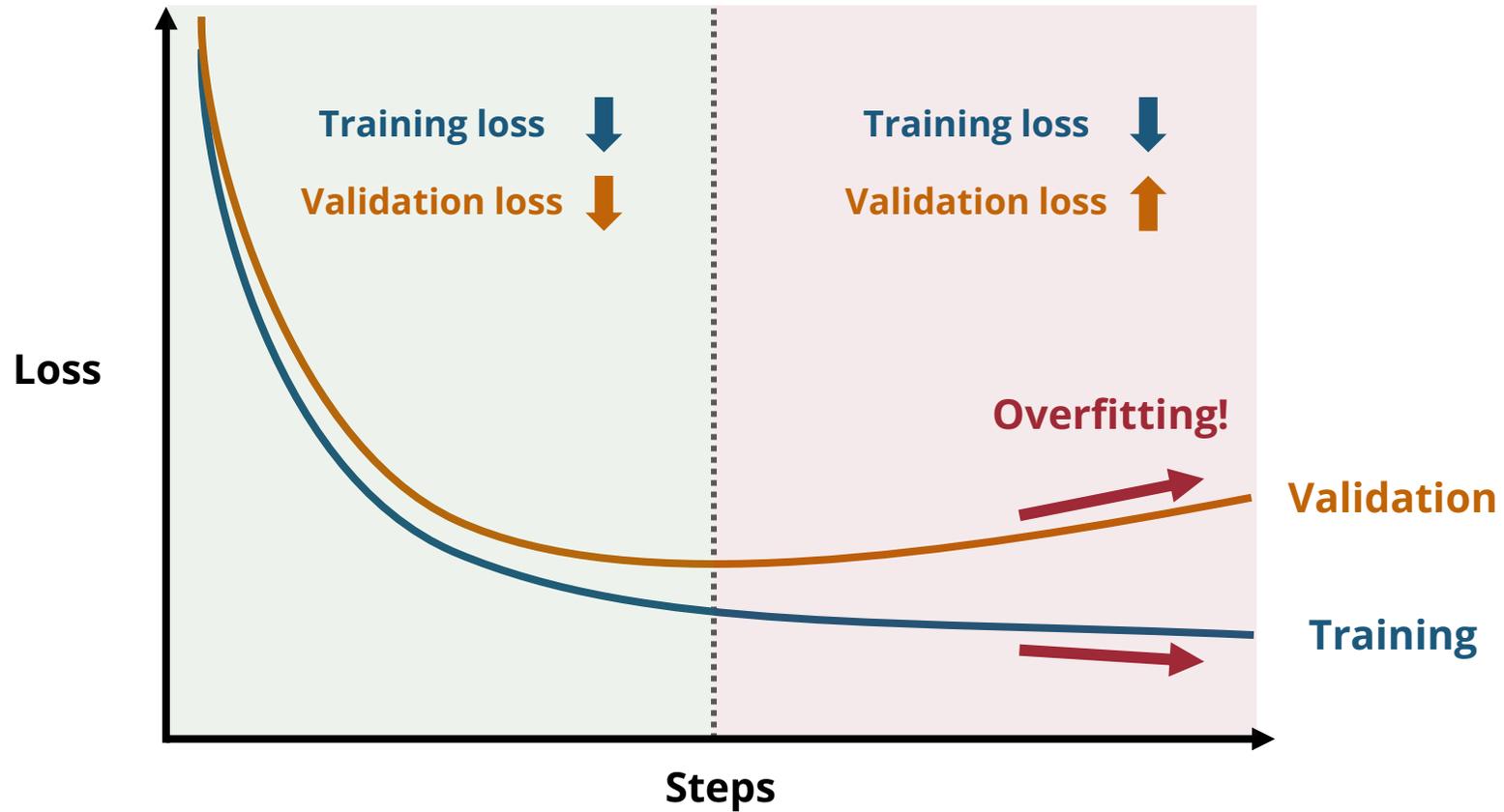


Backward pass
`loss.backward()`

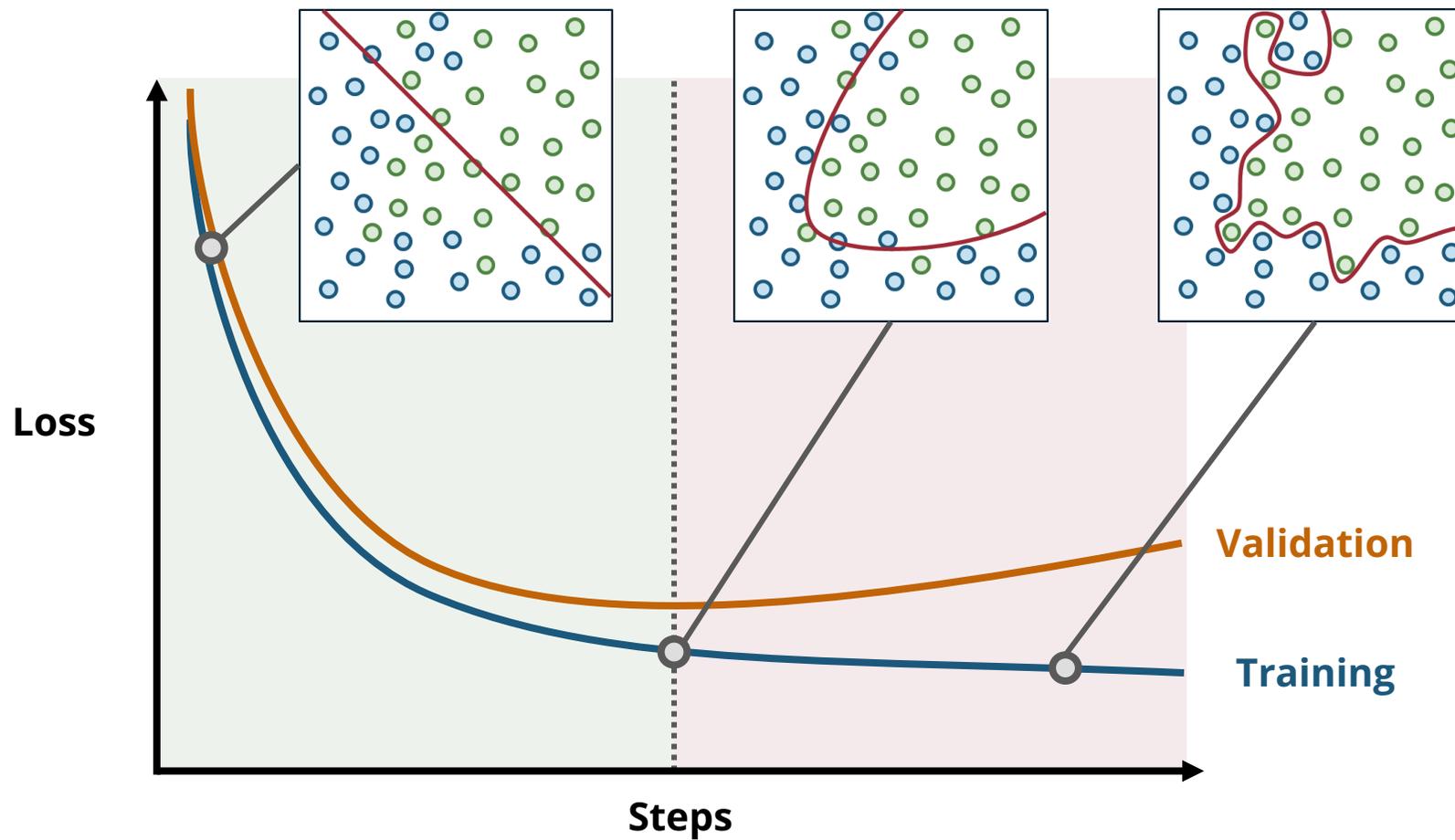
Training-Validation-Test Pipeline



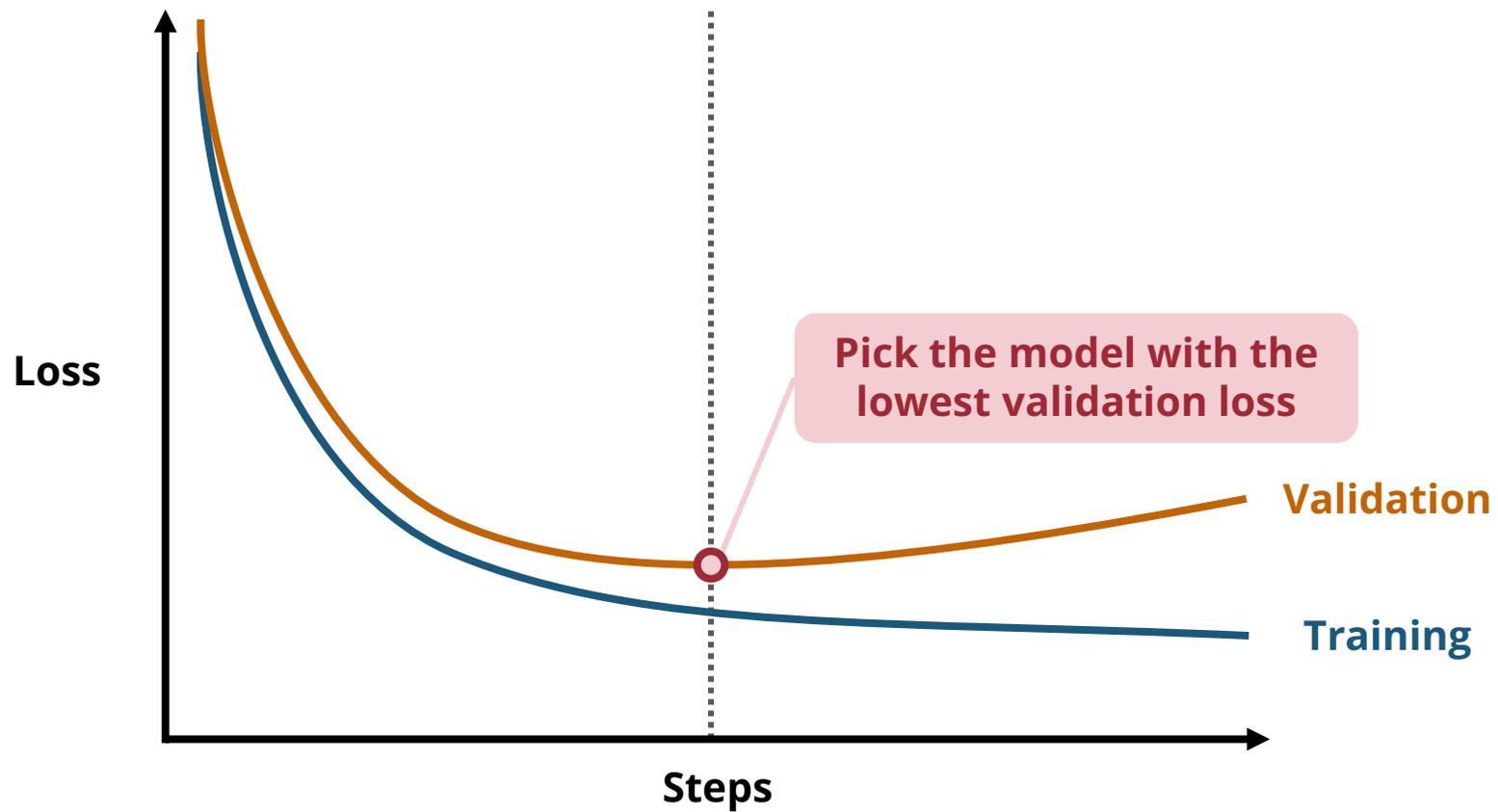
Training vs Validation Losses



Training vs Validation Losses



Training vs Validation Losses



Next Lecture

Deep Generative Models

